

Introduction

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Approximation Algorithms and Linear Programming

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Vertex cover

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$$\begin{aligned} IP : \text{minimize } & \sum_{v \in V} w_v x_v \\ x_u + x_v & \geq 1 \quad \forall (u, v) \in E \\ x_v & \in \{0, 1\} \quad \forall v \in V \end{aligned}$$

$$\begin{aligned} LP : \text{minimize } & \sum_{v \in V} w_v x_v \\ x_u + x_v & \geq 1 \quad \forall (u, v) \in E \\ x_v & \geq 0 \quad \forall v \in V \end{aligned}$$

Matching

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$$D - LP : \text{minimize } \sum_{(u,v) \in E} y_{uv}$$

$$\sum_{v \in N(u)} y_{uv} \leq w_u \text{ for all } u \in V$$

$$y_{uv} \geq 0 \quad \forall v \in V$$

$$M : \text{minimize } \sum_{(u,v) \in E} y_{uv}$$

$$\sum_{v \in N(u)} y_{uv} \leq w_u \text{ for all } u \in V$$

$$y_{uv} \in \{0, 1\} \quad \forall v \in V$$

Set cover

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$$IP : \text{minimize } \sum_{s \in S} w_s x_s$$

$$\sum_{s: v \in s} x_s \geq 1 \quad \forall v \in U$$

$$x_s \in \{0, 1\} \quad \forall s \in S$$

$$LP : \text{minimize } \sum_{s \in S} w_s x_s$$

$$\sum_{s: v \in s} x_s \geq 1 \quad \forall v \in U$$

$$x_s \geq 0 \quad \forall s \in S$$

Set cover: Dual

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$$\begin{aligned} LP : \text{maximize } & \sum_{u \in V} y_u \\ & \sum_{v \in S} y_v \leq w_s \quad \forall s \in S \\ & y_v \geq 0 \quad \forall v \in V \end{aligned}$$

$$\begin{aligned} ILP : \text{maximize } & \sum_{u \in V} y_u \\ & \sum_{v \in S} y_v \leq w_s \quad \forall s \in S \\ & y_v \in \{0, 1\} \quad \forall v \in V \end{aligned}$$

Shortest paths in digraphs

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$$IP : \text{minimize } \sum_{e \in E} w_e x_e$$
$$\sum_{e \in N(v)} x_e = \begin{cases} 1 & \text{if } v = s \\ -1 & \text{if } v = t \\ 0 & \text{otherwise} \end{cases}$$
$$x_e \in \{0, 1\} \quad \forall e \in E$$

Vertex, Edge incidence matrix. (u, e) is 1 if edge goes out from u , -1 otherwise.

LP relaxation polytope is integral (integrality gap is 1).

Constrained shortest paths

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$$\begin{aligned} IP : \text{minimize } & \sum_{e \in E} w_e x_e \\ \sum_{e \in N(v)} x_e = & \begin{cases} 1 & \text{if } v = s \\ -1 & \text{if } v = t \\ 0 & \text{otherwise} \end{cases} \\ & \sum_{e \in E} d_e x_e \leq D \\ & x_e \in \{0, 1\} \forall e \in E \end{aligned}$$

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$$IP_1 : \min \sum_{e \in E} w_e x_e + \lambda \left(\sum_{e \in E} d_e x_e - D \right)$$
$$\sum_{e \in N(v)} x_e = \begin{cases} 1 & \text{if } v = s \\ -1 & \text{if } v = t \\ 0 & \text{otherwise} \end{cases}$$
$$\sum_{e \in E} d_e x_e \leq D$$
$$x_e \in \{0, 1\} \quad \forall e \in E$$

Let x^* be the optimal integral solution to the constrained shortest path problem. $v(IP, x^*) \geq v(IP_1, x^*)$ for $\lambda \geq 0$.

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$$IP_L : \min \sum_{e \in E} w_e x_e + \lambda \left(\sum_{e \in E} d_e x_e - D \right)$$

$$\sum_{e \in N(v)} x_e = \begin{cases} 1 & \text{if } v = s \\ -1 & \text{if } v = t \\ 0 & \text{otherwise} \end{cases}$$
$$x_e \in \{0, 1\} \quad \forall e \in E$$

Let x' be the optimal integral solution to IP_L .

$$v(IP_1, x^*) \geq v(IP_L, x') \quad \forall \lambda \geq 0.$$

Theorem

The value of optimal solution to IP_L is a lower bound on the value of x^ .*

Lagrangian relaxation

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- IP_L is the Lagrangian relaxation.
- We want the best possible lower bound, therefore find λ such that optimal to IP_L maximized.
 - Lagrangian can be solved using subgradient methods (note that the function might not be differentiable).
 - Or using column generation (Dantzig-Wolfe decomposition).
 - Lagrangian bound is atleast as good as the linear programming bound, for integral polytopes the two bounds coincide

Greedy Algorithm for Set Cover

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```
R = {}  
Sol = {}  
while R != U  
    s : min { w(s)/|s \ R| }  
    Sol <- Sol union s  
    R <- R union (s \ R)  
    for all e in (s \ R)  
        p(e) = w(s)/|s \ R|
```

Proof.

$$\sum_{e \in U} p(e) = w(\text{Sol})$$

Consider a set $s = (s_1, \dots, s_k)$

$$\text{For all } i, p(s_i) \leq \frac{w(s)}{k-i}$$

$$\sum_{s_i \in s} p(s_i) \leq w(s)H(k)$$

 $p(e)/H(n)$ is feasible in the dualBy weak duality the performance ratio is $H(n)$. s_i 's are ordered in the order they are covered by the greedy.

LP rounding

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- 1 Construct an integer program for the problem.
- 2 Relax the integrality constraints.
- 3 Solve the linear programming relaxation (in polynomial time).
- 4 Construct an integral solution from the optimal LP solution.

Vertex Cover

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$$\begin{aligned} IP : \text{minimize } & \sum_{v \in V} w_v x_v \\ x_u + x_v & \geq 1 \quad \forall (u, v) \in E \\ x_v & \in \{0, 1\} \quad \forall v \in V \end{aligned}$$

$$\begin{aligned} LP : \text{minimize } & \sum_{v \in V} w_v x_v \\ x_u + x_v & \geq 1 \quad \forall (u, v) \in E \\ x_v & \geq 0 \quad \forall v \in V \end{aligned}$$

Let x^* be the optimal LP solution.

$$x_v = \begin{cases} 1 & \text{if } x_v^* \geq \frac{1}{2} \\ 0 & \text{otherwise.} \end{cases}$$

Vertex Cover

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- Each constraint contains at least one variable with value $\geq 1/2$ in x^* .
- Rounding gives a feasible integral solution.
- Value of the integral solution is at most double the value of the optimal LP solution.

Current best approximation ratio for Vertex Cover. Long standing problem to either improve or show that vertex cover cannot be approximated better than 2 (absolute constant).

Half integrality of Vertex Cover

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Definition

A solution to an LP is an extreme point if it cannot be expressed as a convex combination of two other feasible solutions.

Lemma

Every extreme point solution is half integral i.e., $x_v \in \{0, 1/2, 1\}$.

Proof.

$$a_v = \begin{cases} x_v^* + \varepsilon & \text{if } v \in V_p \\ x_v^* - \varepsilon & \text{if } v \in V_n \\ x_v^* & \text{otherwise.} \end{cases} \quad V_p = \{v \mid x_v^* > 1/2\} \quad V_n = \{v \mid x_v^* < 1/2\}$$
$$b_v = \begin{cases} x_v^* - \varepsilon & \text{if } v \in V_p \\ x_v^* + \varepsilon & \text{if } v \in V_n \\ x_v^* & \text{otherwise.} \end{cases}$$



Multi processor scheduling

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Definition

Input: n jobs and m machines, p_{ij} is the processing time for job i on machine j .

Problem: Assign each job to a machine so as to minimize the makespan (time by which all the machines finish).

IP : minimize t

$$\sum_{j \in M} x_{ij} = 1 \quad \forall i \in J$$

$$\sum_{i \in J} p_{ij} x_{ij} \leq t \quad \forall j \in M$$

$$x_{ij} \in \{0, 1\} \quad \forall i, j$$

LP : minimize t

$$\sum_{j \in M} x_{ij} = 1 \quad \forall i \in J$$

$$\sum_{i \in J} p_{ij} x_{ij} \leq t \quad \forall j \in M$$

Integrality gap

$$i_T = \{j \mid p_{ij} \leq T\}$$

$IP(T)$: minimize 0

$$\sum_{j \in i_T} x_{ij} = 1 \quad \forall i \in J$$

$$\sum_{i \in J} p_{ij} x_{ij} \leq T \quad \forall j \in M$$

$$x_{ij} \in \{0, 1\} \quad \forall i, j$$

$$LP(T): \sum_{j \in i_T} x_{ij} = 1 \quad \forall i \in J$$

$$\sum_{i \in J} p_{ij} x_{ij} \leq T \quad \forall j \in M$$

$$x_{ij} \geq 0 \quad \forall i, j$$

Plan

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- 1 Guess the optimal makespan T
- 2 Construct an optimal extreme point solution to $LP(T)$.
- 3 Assign fractionally scheduled jobs to machines such that no machines receives more than 1 job.

Step 3, can be performed because of the special structure of the extreme point solution.

Step 3 at most doubles the makespan of the fractional schedule. Therefore the performance ratio is 2.

Extreme point solutions

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Lemma

At most $n + m$ variables are fractional in any extreme point solution.

Proof.

Let r be the total number of linearly independent constraints, whose solution is the extreme point solution. Of these r , at least $r - (n + m)$ should be of the type $x_{ij} \geq 0$, ($x_{ij} = 0$). Therefore atmost $n + m$ variables are non-zero. □

Extreme point solutions

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Definition

Connected graph G on vertex set V has property T , if it has at most $|V|$ edges. Graph G has property T is every connected component has property T . $G = (\{J, M\}, \{(i, j) \mid 1 > x_{ij} > 0\})$

Lemma

G has property T .

Proof.

Extreme point solution restricted to connected component is also extreme point solution to LP(T) restricted to the connected component. Else x is not extreme point. Result follows from the previous Lemma. □

Extreme point solutions

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Definition

Let F be the set of fractionally assigned jobs. H is subgraph of G on $F \cup M$

Lemma

H has property T .

Proof.

Equal number of job vertices and incident edges are removed from G to obtain H . □

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Lemma

H has a perfect matching.

Proof.

Every job vertex has at least two edges incident on it, therefore each leaf is a machine. Pair a machine on the leaf with a job (along the fractional edge). Remove the vertices and the edge from H , subgraph still has property T . If left with even cycle (bipartite graph) then pair off alternate edges. \square

Rectangle Stabbing

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Definition

Given a set of n rectangles the objective is to stab all the rectangles using minimum number of axis parallel lines.

Natural Greedy Algorithm (restricted to points)

- Pick the line that covers the maximum number of points in each iteration.
- Approximation ratio is $O(\log n)$.
- Same analysis as for the set cover.

An example

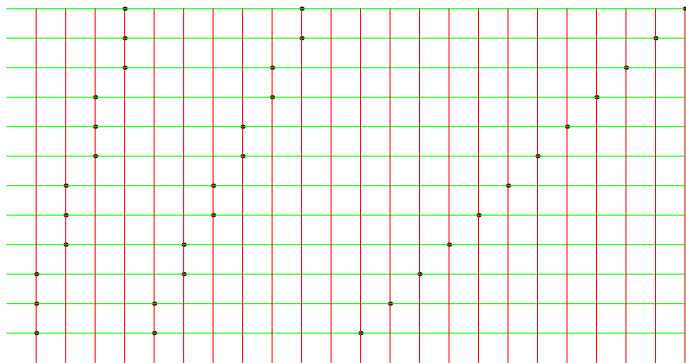
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All the horizontal lines (12) comprise the optimal solution, and the greedy algorithm will pick all the vertical lines (22). The example can be generalized.

Point Stabbing (min-max duality)

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Theorem

The size of the minimum vertex cover is the same as the size of the maximum matching in a bipartite graph.

Point stabbing can be solved optimally.

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L is set of all the lines. $r(H)$ is the set of horizontal lines that intersect rectangle r , $r(V)$ is the set of vertical lines that intersect rectangle r ,

$$\begin{aligned} \min \quad & \sum_{l \in L} w_l x_l \\ & \sum_{l \in r(H)} x_l + \sum_{l \in r(V)} x_l \geq 1 \quad \forall r \\ & x_l \in \{0, 1\} \end{aligned}$$

$$\begin{aligned} P : \min \quad & \sum_{l \in L} w_l x_l \\ & \sum_{l \in r(H)} x_l + \sum_{l \in r(V)} x_l \geq 1 \quad \forall r \\ & x_l \geq 0 \end{aligned}$$

Rectangle stabbing

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x^* is the optimal LP solution.

$$r(*) = \begin{cases} r(V) & \text{if } \sum_{l \in r(H)} x_l^* \geq \frac{1}{2} \\ r(H) & \text{otherwise.} \end{cases}$$

$$M : \min \quad \sum_{l \in L} w_l x_l \\ \sum_{l \in r(*)} x_l \geq 1 \quad \forall r \\ x_l \geq 0$$

Polytope associated with M is integral. $2x^*$ is feasible in M .

Set cover

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Let x^* be the optimal solution.

- 1 Pick each set s in the cover with probability x_s^* .
- 2 Repeat Step 1. $c \log n$ times.

$$E[\text{cost}(\text{setsPicked})] \leq c \log(n) \text{cost}(x^*)$$

$$P[\text{cost}(\text{setsPicked}) > 4c \log(n) \text{cost}(x^*)] \leq 1/4$$

$$\begin{aligned} LP : \text{minimize} \quad & \sum_{v \in V} x_s \\ & \sum_{s: v \in s} x_s \geq 1 \quad \forall v \in U \\ & x_s \geq 0 \quad \forall s \in S \end{aligned}$$

Set Cover

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Lemma

Probability that sets picked do not form a cover $< 1/4$.

Proof.

Let $u \in U$ belong to sets s_1, s_2, \dots, s_k , probability that atleast one of s_1, s_2, \dots, s_k is picked $\sum_{i=1}^k x_i^* \geq 1 - (1 - \frac{1}{k})^k \geq 1 - \frac{1}{e}$ as $\sum_i s_i^* \geq 1$.

Probability that u is not covered after $c \log(n)$ iterations

$$\leq \frac{1}{e^{c \log(n)}} \leq \frac{1}{4n}.$$

Probability that picked sets do not form a cover $\leq n \frac{1}{4n} = \frac{1}{4}$. □

Theorem

Probability that picked sets form a cover with cost atmost $c \log(n)$ times the optimal $\geq 1/2$.

Pricing Method for Vertex Cover

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Definition

$p_e \geq 0$ is the price associated with each edge e .

w_v is the cost associated with each vertex v .

Price p is fair if for every vertex $\sum_{e \text{ on } v} p_e \leq w_v$.

Theorem

A fair price is a lower bound on the cost of any vertex cover.

$$\sum_{e \text{ on } v} p_e \leq w_v$$
$$\sum_{v \in S} \sum_{e \text{ on } v} p_e \leq w(S)$$

Algorithm

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Definition

A vertex is saturated if $\sum_{e \text{ on } v} p_e = w_v$

An edge is uncovered if neither of its endpoints are in the cover.

```
price of e = 0
  while there exists an
    uncovered edge e
      raise price on e
      without violating
      fairness
S = { v | v is saturated}
```


Theorem

Cost of vertex cover produced is at most twice the fair price.

Proof.

Every vertex in the cover is saturated.

$$\begin{aligned}\sum_{e \text{ on } v} p_e &= w_v \\ \sum_{v \in S} \sum_{e \text{ on } v} p_e &= w(S) \\ 2 \sum_e p_e &\geq w(S)\end{aligned}$$



Complementary Slackness

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$$\begin{aligned} P : \min \quad & \sum_{i=1}^n c_i x_i \\ & \sum_{i=1}^n a_{ji} x_i \geq b_j, \quad j = 1..m \\ & x_i \geq 0 \end{aligned}$$

$$\begin{aligned} D : \max \quad & \sum_{j=1}^m b_j y_j \\ & \sum_{j=1}^m a_{ji} y_j \leq c_i, \quad i = 1..n \\ & y_j \geq 0 \end{aligned}$$

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Theorem

Let x, y be primal and dual feasible solutions. x, y are optimal if and only if following conditions are satisfied:

- 1 $x_i(\sum_{j=1}^m a_{ji}y_j - c_i) = 0$ for all $1 \leq i \leq n$
- 2 $y_j(\sum_{i=1}^n a_{ji}x_i - b_j) = 0$ for all $1 \leq j \leq m$.

Relaxed Complementary Slackness

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Definition

Let x, y be primal and dual feasible solutions. x, y are said to satisfy relaxed complementary slackness condition if:

- 1 $x_i > 0 \implies \frac{c_i}{\alpha} \leq \sum_{j=1}^m a_{ji} y_j \leq c_i = 0$ for all $1 \leq i \leq n$
- 2 $y_j > 0 \implies (b_j \leq \sum_{i=1}^n a_{ji} x_i \leq \beta b_j) = 0$ for all $1 \leq j \leq m$.

Theorem

If x, y are feasible and satisfy RCSC then

$$\sum_{i=1}^n c_i x_i \leq \alpha \beta \sum_{j=1}^m b_j y_j.$$

Proof.

$$\begin{aligned} \sum_{i=1}^n c_i x_i &\leq \alpha \sum_{i=1}^n \left(\sum_{j=1}^m a_{ij} y_j \right) x_i \\ \sum_{j=1}^m \left(\sum_{i=1}^n a_{ij} x_i \right) y_j &\leq \beta \sum_{j=1}^m b_j y_j \end{aligned}$$



pricing method for vertex cover revisited

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$$\alpha = 1, \beta = 2$$

$$x_v > 0 \implies \sum_{e \text{ on } v} p_e = w_v$$

$$p_e > 0 \implies x_u + x_v \leq 2$$

- PCSC: Pick only saturated vertices in the cover.
- DCSC: From every edge pick at most two vertices in the cover.

PSCS satisfied by pricing algorithm, DCSC condition satisfied automatically

Minimum Knapsack

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$$\begin{aligned} \min \quad & \sum_{i=1}^n c_i x_i \\ & \sum_{i=1}^n d_i x_i \geq D \\ & x_i \in \{0, 1\} \end{aligned}$$

$$\begin{aligned} D : \max \quad & y_1 D \\ & d_i y_1 \leq c_i \quad \forall i \\ & y_i \geq 0 \end{aligned}$$

Flow cover inequalities

Let F be the set of all the items. Given a set $A \subseteq F$ of items $d(A) = \sum_{a \in A} d_a$, and the residual demand $D(A) = D - d(A)$. Define $d_i(A) = \min\{d_i, D(A)\}$. Items in $F \setminus A$ form another knapsack problem, d_i replaced with $d_i(A)$.

$$\begin{aligned} \min \quad & \sum_{i \in F} c_i x_i \\ \sum_{i \in F \setminus A} d_i(A) x_i & \geq D(A) \quad \forall A \subseteq F \\ x_i & \geq 0 \end{aligned}$$

$$\begin{aligned} \max \quad & \sum_{A \subseteq F} D(A) y_A \\ \sum_{A \subseteq F: i \notin A} d_i(A) y_A & \leq c_i \quad \forall i \in F \\ y_A & \geq 0 \end{aligned}$$

Primal-dual algorithm

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- PCSC: $x_i > 0 \implies \sum_{A \subseteq F: i \notin A} d_i(A) y_A = c_i$
- DSCP: $y_A > 0 \implies \sum_{i \in F \setminus A} d_i(A) x_i \leq 2D(A)$

```
y_{} <- 0
A <- {}
while D(A) > 0 do
    raise y_A until some
    constraint is tight
    x_i <- 1
    A <- A union {i}
end while
S <- A
```

Relaxed complementary slackness

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- Algorithm can raise y_A without violating packing constraint.
- Primal condition is satisfied because algorithm only picks tight elements.
- Let elements in A be $\{1, 2, \dots, k\}$ in the order they are picked.
- At the start $A = \phi$, $d_1(\phi)x_1 + \dots + d_k(\phi)x_k \leq 2D(\phi)$. Consider the point in time when $y_{\{1, 2, \dots, k-1\}}$ was raised, then the first $k-1$ on the LHS in the equation sum to $< D(\phi)$, and the last term is $\leq D(\phi)$.
- The argument holds for any $A = \{1, \dots, i-1\}$, $d_i(A)x_1 + \dots + d_k(A)x_k \leq 2D(A)$.

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