

# Introduction to Computational Geometry

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# Outline

- 1 Introduction
- 2 Area Computation of a Simple Polygon
- 3 Point Inclusion in a Simple Polygon
- 4 Convex Hull: An application of incremental algorithm
- 5 Art Gallery Problem: A study of combinatorial geometry

# Introduction

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- People deal more with **straight or flat objects** (lines, line segments, polygons) or **simple curved objects** as circles, than with high degree algebraic curves.
- This branch of study is around thirty years old if one assumes Michael Ian Shamos's thesis [6] as the starting point.

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- Programming in CG is a little difficult. Fortunately, libraries like **LEDA** [7] and **CGAL** [8] are now available. These libraries implement various data structures and algorithms specific to CG.
- CG algorithms suffer from the curse of degeneracies. So, we would make certain simplifying assumptions at times like **no three points are collinear**, **no four points are cocircular**, etc.

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- First we consider some geometric primitives, that is, problems that arise frequently in computational geometry.

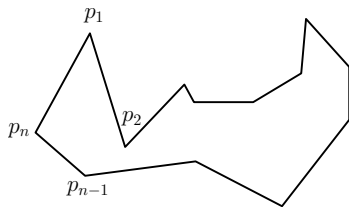
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# Area Computation

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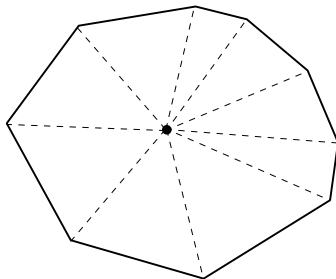
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## Area of a convex polygon

Find a point inside  $P$ , draw  $n$  triangles and compute the area.





# Area Computation

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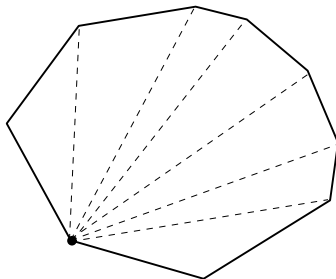
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## A better idea for convex polygon

We can **triangulate**  $P$  by **non-crossing diagonals** into  $n - 2$  triangles and then find the area.



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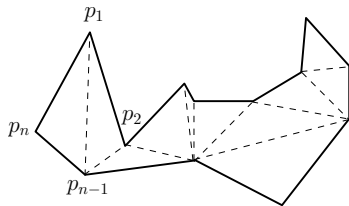
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We can **triangulate**  $P$  by **non-crossing diagonals** into  $n - 2$  triangles and then find the area.

## A better idea for simple polygon

We can do likewise.



# Area Computation

## Result

If  $P$  be a simple polygon with  $n$  vertices with coordinates of the vertex  $p_i$  being  $(x_i, y_i)$ ,  $1 \leq i \leq n$ , then twice the area of  $P$  is given by

$$2\mathcal{A}(P) = \sum_{i=1}^n (x_i y_{i+1} - y_i x_{i+1})$$

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The proof is by induction on  $n$ . □

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## Time complexity

We can **triangulate**  $P$  by a very complicated  $O(n)$  algorithm [2]  
OR by a *more or less simple*  $O(n \log n)$  time algorithm [1].

# Outline

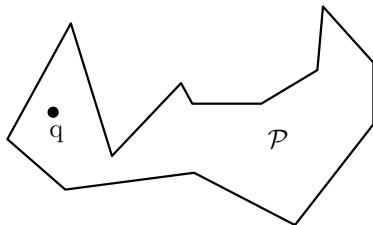
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# Point Inclusion

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Given a simple polygon  $P$  of  $n$  points, and a query point  $q$ , is  $q \in P$ ?



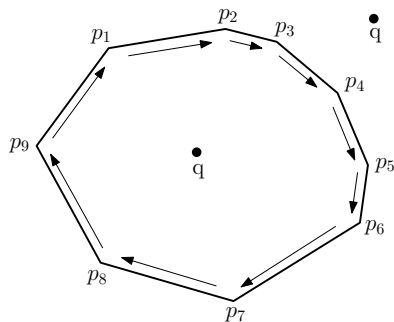
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## What if $P$ is convex?

Easy in  $O(n)$ . Takes a little effort to do it in  $O(\log n)$ . Left as an **exercise**.



$q$  is always to the right if  $q \in P$ ,  
else, it varies

# Point Inclusion

## Problem

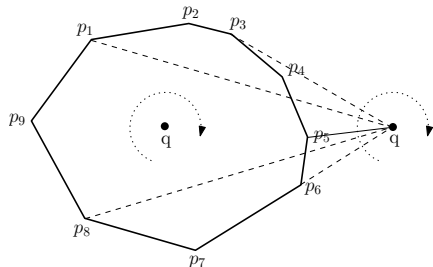
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## Another idea for convex polygon

Stand at  $q$  and walk around the polygon. We can show the same result for a simple polygon also.

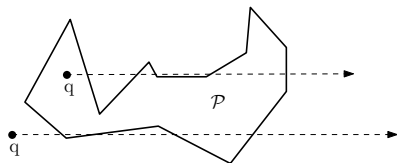


Total angular turn around  $q$  is  $2\pi$  if  $q \in P$ , else, 0

# Point Inclusion

## Another technique: Ray Shooting

Shoot a **ray** and count the number of **crossings** with edges of  $P$ . If it is odd, then  $q \in P$ . If it is even, then  $q \notin P$ . Some degenerate cases need to be handled. Time taken is  $O(n)$ .



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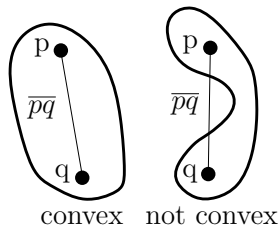
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A set  $S \subset \mathcal{R}^2$  is convex If for any two points  $p, q \in S$ ,  $\overline{pq} \in S$ .

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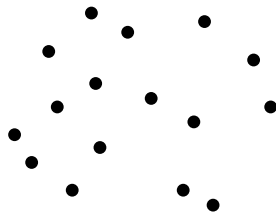
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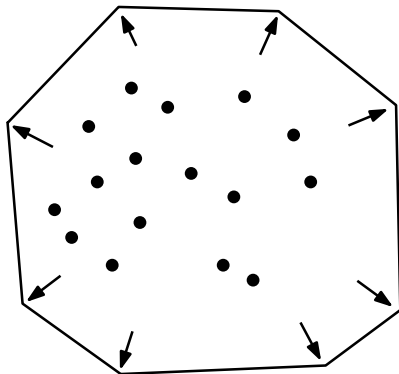
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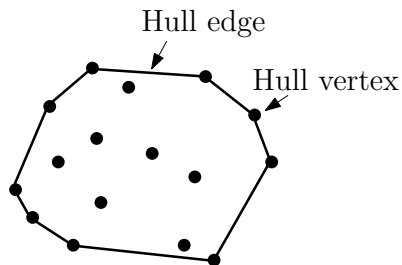
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# Convex Hull Problem

## Problem

*Given a set of points  $\mathcal{P}$  in the plane, compute the convex hull  $CH(\mathcal{P})$  of the set  $\mathcal{P}$ .*

# A Naive Algorithm

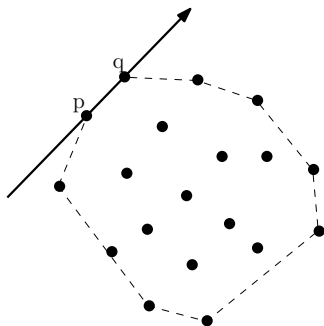
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- Consider all line segments determined by  $\binom{n}{2} = O(n^2)$  pairs of points.

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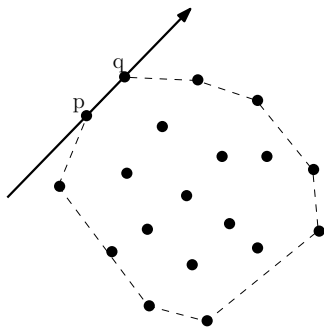
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- If a line segment has all the other  $n - 2$  points on one side of it, then it is a hull edge.



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- If a line segment has all the other  $n - 2$  points on one side of it, then it is a hull edge.
- We need  $\binom{n}{2}(n - 2) = O(n^3)$  time.



# Towards a Better Algorithm

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- How much better can we make?
- Leads to the notion of **lower bound of a problem**.
- The problem of Convex Hull has a lower bound of  $\Omega(n \log n)$ .  
This can be shown by a reduction from the problem of sorting which also has a lower bound of  $\Omega(n \log n)$ .

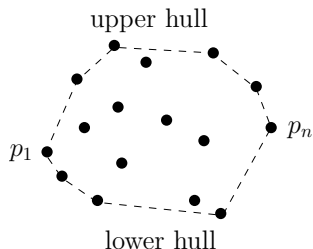
# Optimal Algorithms

- **Grahams scan**, time complexity  $O(n \log n)$ .  
(Graham, R.L., 1972)
- **Divide and conquer algorithm**, time complexity  $O(n \log n)$ .  
(Preparata, F. P. and Hong, S. J., 1977)
- **Jarvis's march** or **gift wrapping algorithm**, time complexity  $O(nh)$  where  $h$  is the number of vertices of the convex hull.  
(Jarvis, R. A., 1973)
- Most efficient algorithm to date is based on the idea of Jarvis's march, time complexity  $O(n \log h)$ .  
(T. M. Chan, 1996)

# Definitions

## A better characterization

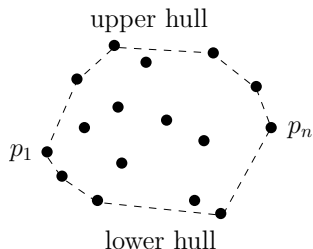
- Consider a walk in clockwise direction on the vertices of a closed polygon.



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## A better characterization

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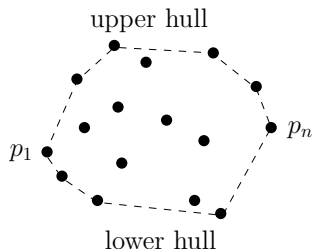


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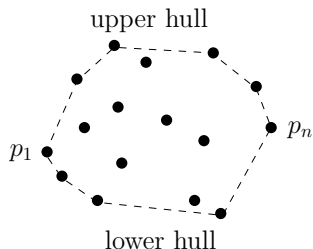
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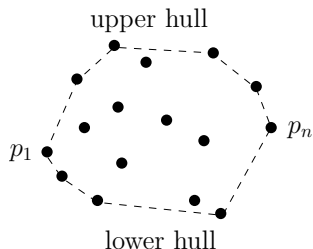
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- We compute the upper hull first. The upper hull contains the convex hull edges that bound the convex hull from above.



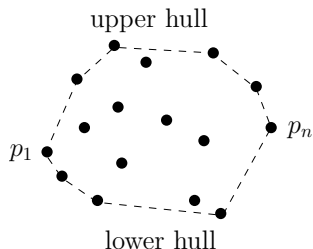
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- Sort the points in  $\mathcal{P}$  from left to right.



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for  $i = 3$  to  $n$  {

    Append  $p[i]$  to  $L_U$ ;

    while( $L_U$  contains more than two points AND

        the last three points in  $L_U$

        do not make a right turn) {

    }

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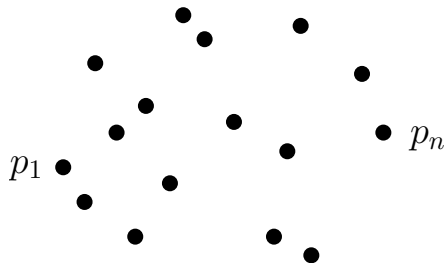
Delete the middle of the last

three points from  $L_U$ ;

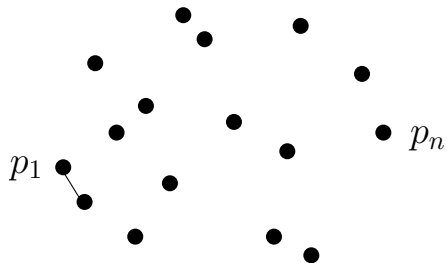
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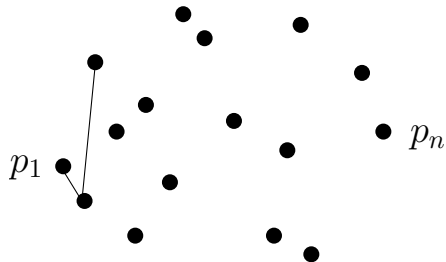
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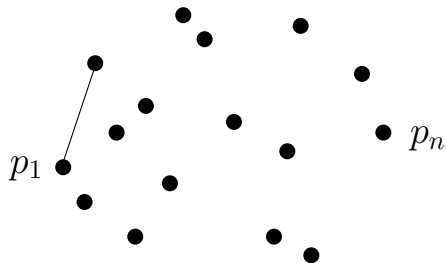
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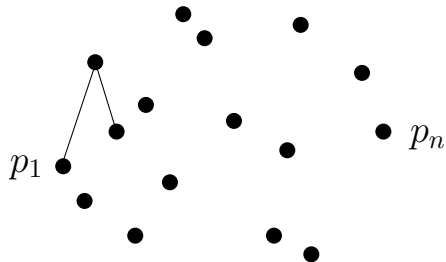
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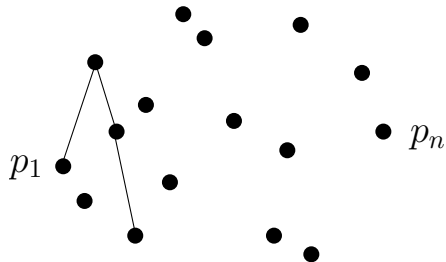
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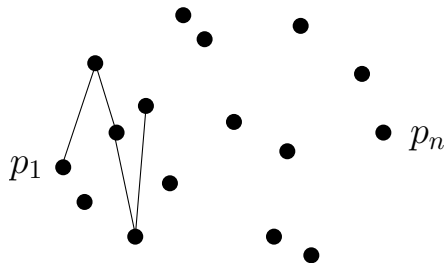


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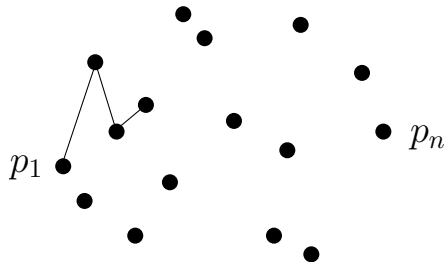




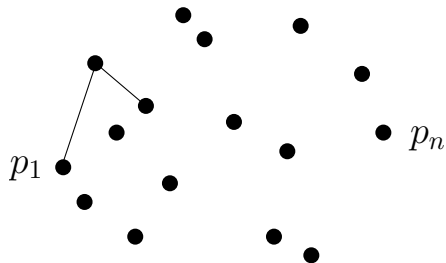
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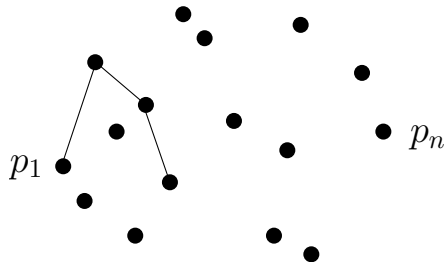
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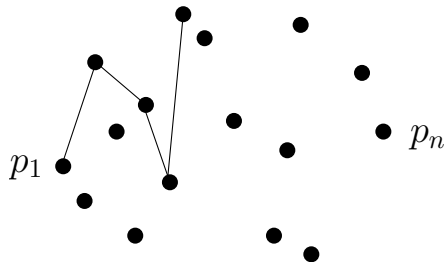
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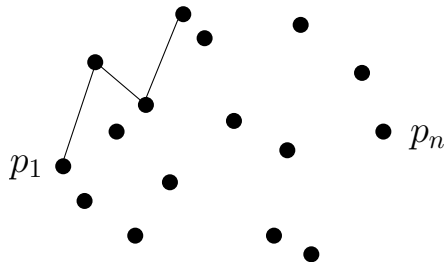
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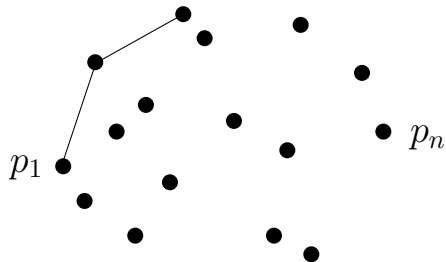
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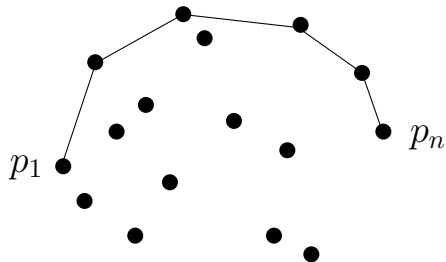
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# Analysis

## Time complexity

- Sorting takes time  $O(n \log n)$ .

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- Hence, the total time complexity is  $O(n \log n)$ .

# Outline

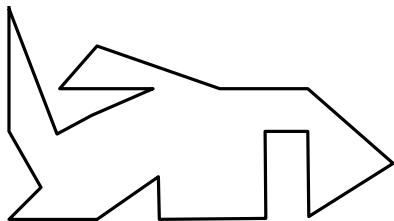
- 1 Introduction
- 2 Area Computation of a Simple Polygon
- 3 Point Inclusion in a Simple Polygon
- 4 Convex Hull: An application of incremental algorithm
- 5 Art Gallery Problem: A study of combinatorial geometry**



# Art Gallery Problem

## The problem

Given a simple polygon  $\mathcal{P}$  of  $n$  vertices, find the minimum number of cameras that can guard  $\mathcal{P}$ .



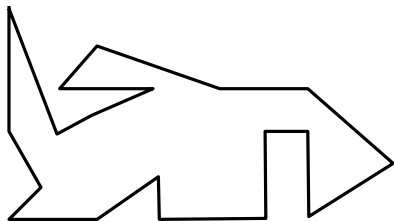
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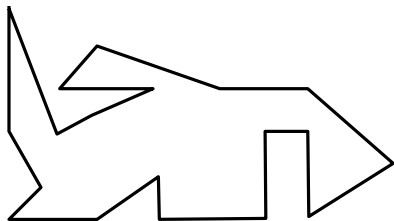
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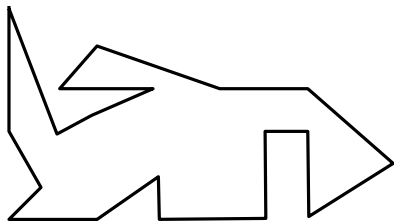
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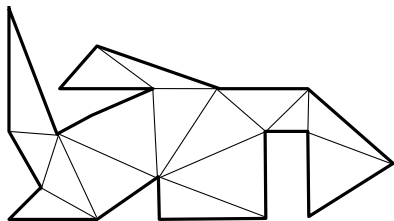
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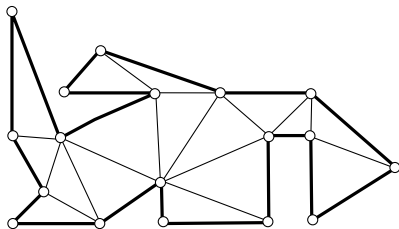
- Can we find, as a function of  $n$ , the number of cameras that suffices to guard  $\mathcal{P}$ ?
- Recall  $\mathcal{P}$  can be triangulated into  $n - 2$  triangles. Place a guard in each triangle.



# Art Gallery Problem

Can the bound be reduced?

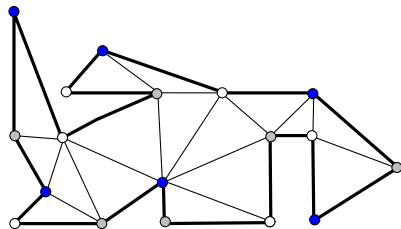
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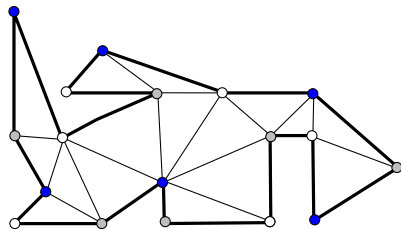
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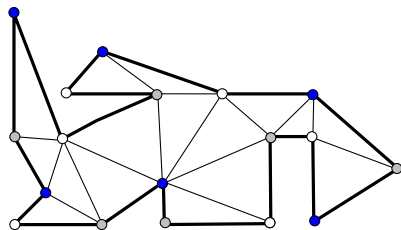




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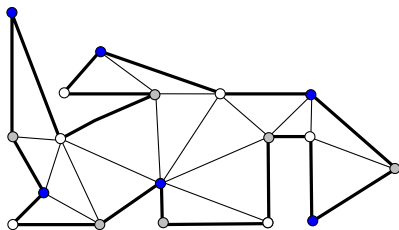
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- Hence,  $\lfloor \frac{n}{3} \rfloor$  guards suffice.



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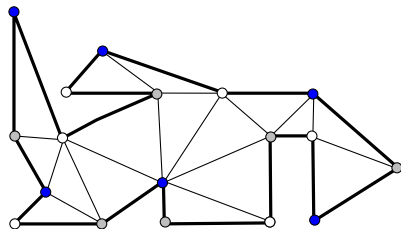
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- Choose the smallest color class to guard  $\mathcal{P}$ .
- Hence,  $\lfloor \frac{n}{3} \rfloor$  guards suffice.
- But, does a 3-coloring always exist?



# Art Gallery Problem

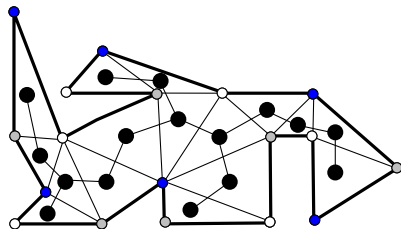
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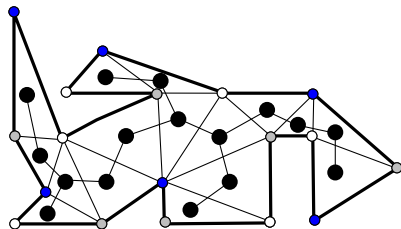
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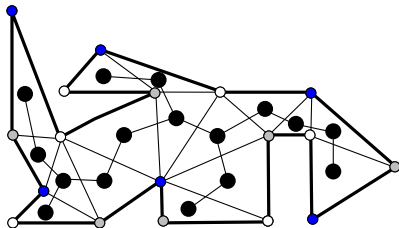
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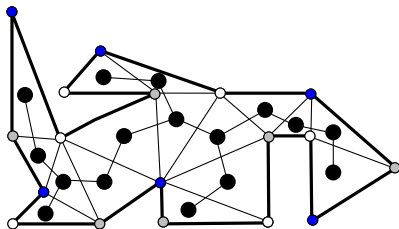
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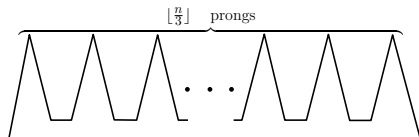
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## Necessity?

Are  $\lfloor \frac{n}{3} \rfloor$  guards sometimes necessary?









# Art Gallery Theorem

## Final Result

For a simple polygon with  $n$  vertices,  $\lfloor \frac{n}{3} \rfloor$  cameras are always sufficient and occasionally necessary to have every point in the polygon visible from at least one of the cameras.

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# References II



<http://www.algorithmic-solutions.com>



<http://www.cgal.org>



[http://en.wikipedia.org/wiki/Computational\\_geometry](http://en.wikipedia.org/wiki/Computational_geometry)

Thank you!