Tree Path Labeling of Set Systems

A Generalization of Consecutive Ones Property

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Outline



- Illustration
- Motivation
- 2 Characterization
 - Feasible Tree Path Labeling
- Computation of Feasible Tree Path Labeling
 On k-subdivided Stars

Conclusion Application

Characterization Computation of Feasible Tree Path Labeling Conclusion Illustration Motivation

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A Study Group Housing problem

- A set {a, b, c, d, e, f, g, h, i, j, k} of n students arrive for a summer course. They form m study groups {R, B, O, G}.
- A student is in at least one study group, *R* = {*g*, *h*, *i*, *j*, *k*}, *B* = {*a*, *b*, *e*, *g*}, *O* = {*c*, *b*, *d*}, *G* = {*e*, *f*, *g*, *i*}
- There are *n* single occupancy apartments in the university campus for their accommodation.
- All these apartments are placed such that streets connecting them do not form loops

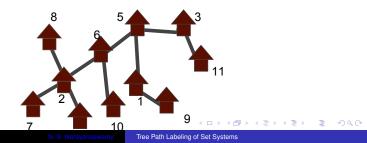


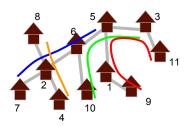
Illustration Motivation

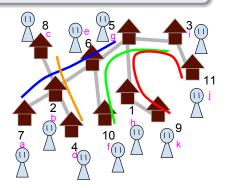
A Study Group Housing problem

The problem

How should the students be allocated apartments such that each study group has consecutive apartments allocated?

Conclusion





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Tree Path Labeling(TPL) of Set Systems

The combinatorial problem terminology

Terminology

- The set of study groups i.e. sets of students \rightarrow SET system / Hypergraph
- The streets with apartments \rightarrow TARGET TREE
- The route mapping to study groups → TREE PATH LABELING (TPL)
- The apartment allocation → PATH HYPERGRAPH ISOMORPHISM

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Tree Path Labeling of Set Systems

The combinatorial problem

Terminology [contd.]

There exists an apartment allocation that "fits" the route mapping

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The combinatorial problem

Terminology [contd.]

There exists a hypergraph isomorphism that "fits" the TPL

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The combinatorial problem

Terminology [contd.]

There exists a hypergraph isomorphism that "fits" the TPL \rightarrow the TPL is FEASIBLE

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The combinatorial problem

Terminology [contd.]

There exists a hypergraph isomorphism that "fits" the TPL \rightarrow the TPL is FEASIBLE

There *exists* an apartment allocation that gives the required route mapping

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The combinatorial problem

Terminology [contd.]

There exists a hypergraph isomorphism that "fits" the TPL \rightarrow the TPL is <code>FEASIBLE</code>

There *exists* a hypergraph isomorphism that gives paths/adjacent vertices in tree

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The combinatorial problem

Terminology [contd.]

There exists a hypergraph isomorphism that "fits" the TPL \rightarrow the TPL is <code>FEASIBLE</code>

There *exists* a hypergraph isomorphism that gives paths/adjacent vertices in tree

 \rightarrow the hypergraph is a PATH HYPERGRAPH

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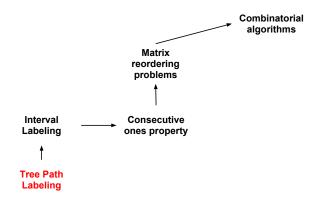


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Consecutive Ones → Path Labeling



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Consecutive Ones Property(COP) Does a 0-1 Matrix have COP?

Does there exist a permutation of rows such that ones in each column occur consecutively?

$$\begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

COP is equivalent to interval assignment to a set system

Given,

- **()** a set \mathcal{F} of subsets of a finite set U of cardinality n,
- an assignment of intervals of the discrete set {1,..., n} to each element of *F*

Does there exist a bijection $\phi : U \to \{1, ..., n\}$ such that for each element of \mathcal{F} , its image under ϕ is same as the interval assigned to it?

Introduction Characterization

Illustration Motivation

Interval Assignment to Set System

Computation of Feasible Tree Path Labeling

An interval assignment $I : \mathcal{F} \to I$ to \mathcal{F} is called *feasible* if there exists such a bijection ϕ .

$$\begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

 $\mathcal{F}: \{1,3\}, \{1,5\}, \{1,3,5\}, \{2,4,5\} \Rightarrow \textit{I}: [12], [23], [13], [35]$

Characterization of Feasible Interval Assignments

An interval assignment is feasible if and only if it is an Intersection Cardinality Preserving Interval Assignment (ICPIA)

$$I: \mathcal{F} \to I$$
 is an ICPIA if

2
$$|S_i \cap S_j| = |I(S_i) \cap I(S_j)|$$
, for all $S_i, S_j \in \mathcal{F}$

Characterization Computation of Feasible Tree Path Labeling Conclusion Illustration Motivation

Path Assignment to Set System

Given,

- **()** a set system \mathcal{F} of a finite set U of cardinality n, a tree T of size n
- 2 a bijection called *tree path labeling*, l mapping the sets in \mathcal{F} to paths in T

Question

Does there exist a bijection $\phi : U \to V(T)$ such that for each $S \in \mathcal{F}$, $\{\phi(x) \mid x \in S\} = \ell(S)$?

- A tree path labeling of a set system is called *feasible* if there exists such a bijection ϕ
- If the path assignment is feasible, then all way intersection cardinalities are preserved
- For trees that are paths, pairwise intersection cardinality is sufficient to guarantee that all way intersection cardinality is preserved. Can we extend this idea to aribtrary trees?

Characterization Computation of Feasible Tree Path Labeling Conclusion

Feasible Tree Path Labeling

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Feasible Tree Path Labeling

Feasible Tree Path Labeling

An Algorithmic Characterization

Feasible Tree Path Labeling

A path labeling is feasible if and only if it is an ICPPL and it successfully passes the filtering algorithms 1 and 2.

Path Labeling $I: \mathcal{F} \to \mathcal{P}$ for set system \mathcal{F} and path system \mathcal{P} . *I* is an Intersection Cardinality Preserving Path Labeling (ICPPL) if

$$\bigcirc |S_i| = |I(S_i)|, \text{ for all } S_i \in \mathcal{F}$$

$$2 |S_i \cap S_j| = |I(S_i) \cap I(S_j)|, \text{ for all } S_i, S_j \in \mathcal{F}$$

Given an ICPPL,

- Filter 1 processes the set and path system such that there are no
 2 sets whose images share a leaf of the tree
- Pilter 2 assigns set elements to leaves of the tree
- Prune the tree of its leaves and recurse

Filter 1: Process Sets whose images share a leaf

Algorithm 1 Refine ICPPL filter_1(\mathcal{F}, ℓ, T)

while $\exists S_1, S_2 \in \mathcal{F}$ whose images share a leaf of T do Remove S_1 , S_2 from \mathcal{F} Add the "filtered" sets $\{S_1 \cap S_2, S_1 \setminus S_2, S_2 \setminus S_1\}$ to \mathcal{F} Retain path labeling of sets other than S_1 and S_2 $\ell(S_1 \cap S_2) \leftarrow \ell(S_1) \cap \ell(S_2)$ $\ell(S_1 \setminus S_2) \leftarrow \ell(S_1) \setminus \ell(S_2)$ $\ell(S_2 \setminus S_1) \leftarrow \ell(S_2) \setminus \ell(S_1)$ if (\mathcal{F}, ℓ) does not satisfy condition (3) of ICPPL then exit end if end while return \mathcal{F} . l

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Filter 2: Assign Set Elements to Leaves

Algorithm 2 Leaf Labeling filter_2 (\mathcal{F} , ℓ , T)

```
Path images are such that no two path images share a leaf
while there is a leaf v \in T and a S_1 \in \mathcal{F} s.t v \in \ell(S_1) do
   Remove S_1 from \mathcal{F}
   Retain path labeling of sets in \mathcal{F} other than S_1
   Let X be the set of elements present only in S_1
   if X is empty then
      exit
   end if
   x \leftarrow \text{arbitrary element from } X
   Add \{x\} and S_1 \setminus \{x\} to \mathcal{F}
   l(\{x\}) \leftarrow \{v\}
   \ell(S_1 \setminus \{x\}) \leftarrow \ell(S_1) \setminus \{v\}
end while
return \mathcal{F}.
```

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Feasible Tree Path Labeling

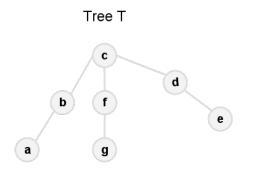
Feasible Tree Path Labeling

Algorithm 3 get-feasible-permutation (\mathcal{F}, l, T)

```
Call filter 1 to pre-process (\mathcal{F}, \ell)
Call filter 2 to obtain pre-images for leaves of T
for every leaf v \in T do
   \phi(x) \leftarrow v where x \in \ell^{-1}(\{v\})
end for
L \leftarrow \{v \mid v \text{ is a leaf in } T\}
For each v \in L, remove \{v\} and I(\{v\}) = \{x\} from \mathcal{F} and \ell
T \leftarrow T \setminus L
if T is not empty then
   \phi \leftarrow \phi \cup \text{get-feasible-permutation}(\mathcal{F}, \ell, T)
end if
return \phi
```

Feasible Tree Path Labeling

An Example: Input Instance



 $F = \{ \{3,4,6\}, \{2,3,4,5\}, \{3,4,6,7\}, \{1,2,3\}, \{3,4,5,6,7\} \} \\ P = \{ \{d,c,f\}, \{e,d,c,b\}, \{d,c,f,g\}, \{c,b,a\}, \{e,d,c,f,g\} \}$

Figure: Set System and Corresponding Paths (labeling is in the given order)

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Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

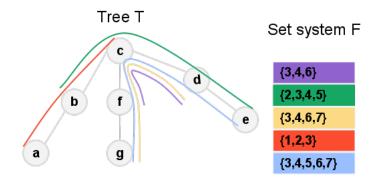


Figure: Paths gfcd, gfcde share leaf g

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

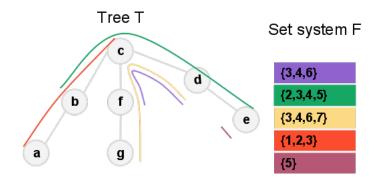


Figure: New set {5} created. bcde, e share leaf e.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

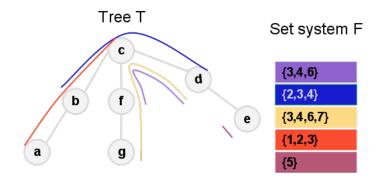


Figure: New set {2,3,4} created. No more leaves shared.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

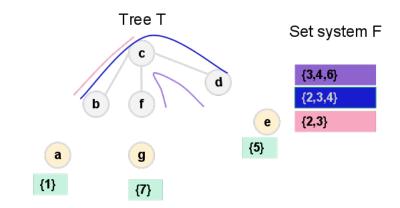


Figure: Leaf assignment done and leaves pruned. Paths *bcd*, *fcd* share leaf *d*.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

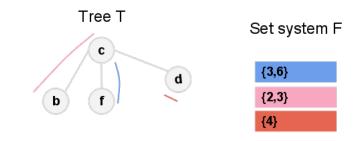




Figure: New set {4} created. No more leaves shared.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

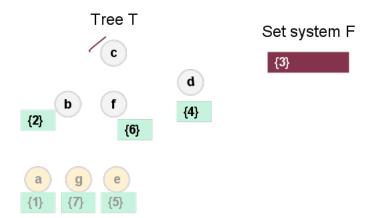


Figure: Leaf assignment done and leaves pruned.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

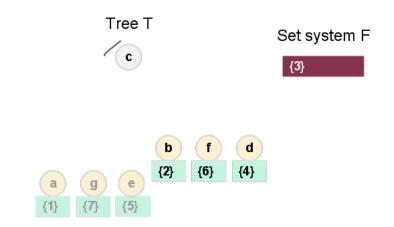


Figure: Only single node left in T.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

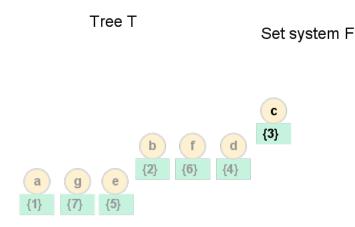


Figure: Labeling is obvious.

Feasible Tree Path Labeling

An Example: Output of Filtering Algorithms

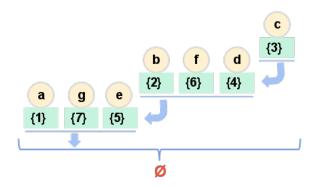


Figure: Recursively computed bijection ϕ

On k-subdivided Stars

Outline



Application

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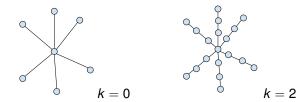
On k-subdivided Stars

TPL from a *k*-subdivided star

Computing a feasible TPL

Given hypergraph \mathcal{F} with certain properties and a *k*-subdivided star T, can we find a feasible TPL ℓ to T?

A *k*-subdivided star is a star with all its edges subdivided exactly *k* times.



On k-subdivided Stars

TPL from a k-subdivided star Special case: Interval assignment(COP) problem

- T is a path \implies paths in T are intervals
- Only pairwise intersection cardinality needs to be preserved: ICPIA
- Higher level intersection cardinalities preserved by Helly Property
- filter_1, filter_2 do not need the exit conditions.

This problem is equivalent to Consecutive Ones Property of binary matrices

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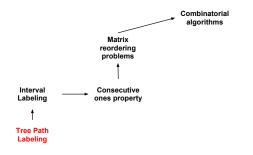




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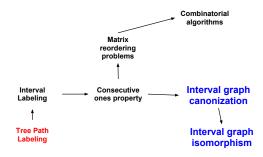
Application

Path Labeling → Graph Isomorphism Application



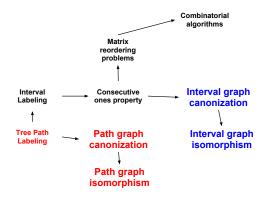
Application

Path Labeling → Graph Isomorphism Application



Application

Path Labeling → Graph Isomorphism Application



Application

References

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Thank You!

Application

Questions?

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