Sketching Streams

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Stream is a sequence of records

- Arrives fast, continuously.
- Not enough main memory to store stream.
- Too fast to store on secondary storage with random access. May be stored as a log file for later mining.



Network switch data (Distr. Denial of Service brewing?)

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- Sensor networks (intrusion?)
- Satellite data (storm? flashflood?)
- Others: web-usage, financial market, etc.

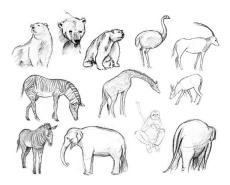
- Low space data structure: Sub-linear/ poly-logarithmic in stream size.
- Process each arriving record efficiently to match fast arrival speeds.
- Online Processing: input record is processed as it arrives.
- Streaming Model: Online, sub-linear space and time processing.
- Other Models: not in this talk.
 - Semi-Streaming: Stores data in sequential order. Multiple passes are allowed.

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This talk

Some algorithmic techniques have evolved for data stream processing. We will see some important ones:

Linear Sketching, Dimensionality Reduction.



Sampling from Data Streams: Not covered



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Data Stream Model

- Domain of items $[n] = \{1, 2, ..., n\}.$
- n is known but very large : IP-addresses, pairs of IP-addresses—2⁶⁴.
- ► Insert-Delete Streams: Sequence of updates (*item*, *change in frequency*) ≡ (*i*, *v*).

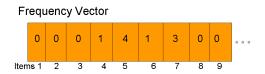
(1,1) (4,1) (5,3) (7,1) (5,-1) (5,2) (7,2) (6,1) (1,-1) ...

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Frequency Vector

(1,1) (4,1) (5,3) (7,1) (5,-1) (5,2) (7,2) (6,1) (1,-1) ...



Incremental view:

- 1. Initially f = 0.
- 2. When (i, v) arrives:

$$f_i:=f_i+v$$
.

Global view:

$$f_i = \sum_{(i,v)\in ext{ stream }} v, \ i \in [n]$$
 .

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- Single pass over stream (Online algorithm).
- Sublinear storage: n^α (α < 1) or, better poly-logarithmic in n.
 - Units of storage: bits.
- ► Fast processing per arriving stream record.
 - Approximate processing (almost always necessary).
 - Randomized computation (almost always necessary).

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- ► Independence: Random variables {X₁, X₂,..., X_n} are independent if their joint probability (density) function is the product of individual probability (density) function.
- Computational Problems:
 - Design h: [n] → {0,1} so that {h(1),...,h(n)} are independent. All constructions require Ω(n) random bits.

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- High randomness and storage.
- Algorithms may not always require full independence.
- Approximate independence often suffices.

 $\{X_1, X_2, \ldots, X_n\}$ are *k*-wise independent if the joint distribution of any *k* variables is the product of their individual distributions.

$$\Pr \left\{ X_{i_1} = a_1 \land X_{i_2} = a_2 \land \ldots \land X_{i_k} = a_k \right\} \\ = \Pr \left\{ X_{i_1} = a_1 \right\} \Pr \left\{ X_{i_2} = a_2 \right\} \ldots \Pr \left\{ X_{i_k} = a_k \right\} ...$$

for any *k* distinct indices $1 \le i_1, i_2, \ldots, i_k \le n$ and $a_1 \in \text{support}(X_{i_1}), \ldots, a_k \in \text{support}(X_{i_k})$.

- Product of expectation of any k distinct variables is the product of individual expectations.
- *k*-wise independence implies k 1-wise indep.

[Wegman Carter JCSS 81]

- \mathcal{H} is a finite family of functions mapping $[n] \rightarrow [m]$.
- Pick random member $h \in \mathcal{H}$ with prob. $1/|\mathcal{H}|$.
- ► Equivalently, for distinct $x_1, x_2, ..., x_k \in [n]$ and $b_1, ..., b_k \in [m]$ not necessarily distinct,

$$\Pr_{h\in\mathcal{H}} \{ (h(x_1) = b_1) \land (h(x_2) = b_2) \dots \land (h(x_k) = b_k) \}$$

 $\Pr_{h\in\mathcal{H}} \{h(x_1) = b_1\} \cdot \Pr_{h\in\mathcal{H}} \{h(x_2 = b_2)\} \cdots \times \Pr_{h\in\mathcal{H}} \{h(x_k) = b_k\} .$

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- \mathbb{F} is a finite field of size at least *n*.
- \mathcal{H}_k : set of all *k*-tuples from \mathbb{F} . So $|\mathcal{H}_k| = |\mathbb{F}|^k$.
- Interpret a k-tuple (a₀,..., a_{k-1}) as a degree k − 1 polynomial p(x) over F:

$$p(x) = a_0 + a_1 x + a_2 x^2 + \ldots + a_{k-1} x^{k-1}$$

• The family \mathcal{H}_k is k-wise independent.

- $|\mathcal{H}_k| = |\mathbb{F}|^k$.
- Requires $k \log |\mathbb{F}|$ bits to store a polynomial from \mathcal{H}_k .
- ► Randomness required: choose a₀,..., a_k at random-k log|𝔅| random bits.
- ► $h(\cdot)$ can be computed in time O(k) field operations $(+, \cdot)$.
- ► Special Case. \mathcal{H}_2 : space of affine functions over \mathbb{F}

$$h(x) = a_0 + a_1 x$$
, $a_0, a_1 \in F$.

Pair-wise independence.

"Pair-wise independence and Derandomization", Luby and Wigderson (web)

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Frequency moment defined as

$$F_{\mathcal{P}} = \sum_{i \in [n]} |f_i|^k$$
 .

 $p \in \mathbb{R}$ and non-negative.

- The problem of estimating frequency moments has played an important role in data stream computations.
- ► *F*₀ is the number of distinct elements in the stream

$$F_0 = \sum_{i \in [n]} |f_i|^0 = |\{i : f_i \neq 0\}|$$
.

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[Alon Matias Szegedy: STOC'96, JCSS '98.]

- Deterministically estimating F₂ to within 1 ± 1/16 requires Ω(n) space.
- Modified problem: Given ε and δ, design an algorithm that returns F₂ satisfying

$$|\hat{F}_2 - F_2| \leq \epsilon F_2$$
 with prob. 1 $-\delta$.

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- Let $\xi : [n] \to \{-1, +1\}$
 - $\xi(\cdot)$ four-wise independent hash function.
 - Maps to ± 1 with equal probability.
- ► Implementation: Choose *h* at random from the family of cubic polynomials over F_{2^r}, where, n ≤ 2^r < 2n.</p>

$$\xi(u) = \begin{cases} 1 & \text{if last bit of } h(u) = 1 \\ -1 & \text{otherwise.} \end{cases}$$

A sketch is a linear combination

$$X=\sum_{i=1}^n f_i\xi(i) \ .$$

Updating sketch in presence of stream updates:

UPDATESKETCH
$$(i, v)$$
: $X := X + v \cdot \xi(i)$

Sketches

Sketch: $\sum_{i} f_i \xi(i), \xi : [n] \to \{-1, +1\}$ four wise independent.

$$\mathbb{E}\left[\xi(i)\right] = (-1)\frac{1}{2} + (1)\frac{1}{2} = 0$$

We now calculate $\mathbb{E}[X^2]$.

$$\mathbb{E}\left[X^{2}\right] = \mathbb{E}\left[\left(\sum_{i=1}^{n} f_{i}\xi(i)\right)^{2}\right]$$
$$= \mathbb{E}\left[\sum_{i=1}^{n} f_{i}^{2}(\xi(i))^{2} + 2\sum_{1 \le i < j \le n} f_{i}f_{j}\xi(i)\xi(j)\right]$$
$$= \sum_{i=1}^{n} f_{i}^{2}\mathbb{E}\left[(\xi(i))^{2}\right] + 2\sum_{1 \le i < j \le n} f_{i}f_{j}\mathbb{E}\left[\xi(i)\xi(j)\right]$$

using linearity of expectation.

We have shown that

$$\mathbb{E}\left[X^2\right] = \sum_{i=1}^n f_i^2 \mathbb{E}\left[(\xi(i))^2\right] + 2\sum_{1 \le i < j \le n} f_i f_j \mathbb{E}\left[\xi(i)\xi(j)\right] .$$

▶ Now, $(\xi(i))^2 = 1$, and by pair-wise independence, if $i \neq j$,

$$\mathbb{E}\left[\xi(i)\xi(j)\right] = \mathbb{E}\left[\xi(i)\right]\mathbb{E}\left[\xi(j)\right] = \mathbf{0}\cdot\mathbf{0} = \mathbf{0} \ .$$

Therefore, we get an unbiased estimator.

$$\mathbb{E}\left[X^2\right] = \sum_{i=1}^n f_i^2 = F_2 \ .$$

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Sketch:Variance

$$\mathbb{E}\left[X^{4}\right] = \mathbb{E}\left[\left(\sum_{i=1}^{n} f_{i}\xi(i)\right)^{4}\right]$$
$$= \mathbb{E}\left[\sum_{i=1}^{n} f_{i}\xi(i)\sum_{j=1}^{n} f_{j}\xi(j)\sum_{k=1}^{n} f_{k}\xi(k)\sum_{l=1}^{n} f_{l}\xi(l)\right]$$

Expanding

$$\mathbb{E}\left[X^{4}\right] = \mathbb{E}\left[\sum_{i=1}^{n} f_{i}^{4}\xi(i)^{4} + \sum_{i \neq j} 4f_{i}^{3}f_{j}(\xi(i))^{3}\xi(j) + \sum_{i,j \text{ distinct}} 6f_{i}^{2}f_{j}^{2}\xi(i)^{2}\xi(j)^{2} + \sum_{i,j,k \text{ distinct}} 12f_{i}^{2}f_{j}f_{k}\xi(i)^{2}\xi(j)\xi(k) + \sum_{i,j,k,l \text{ distinct}} 4!f_{i}f_{j}f_{k}f_{l}\xi(i)\xi(j)\xi(k)\xi(l)\right]$$

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Sketch: Variance

Using linearity of expectation

$$\mathbb{E} \left[X^{4} \right] = \sum_{i=1}^{n} f_{i}^{4} \mathbb{E} \left[\xi(i)^{4} \right] + \sum_{i \neq j} 4f_{i}^{3} f_{j} \mathbb{E} \left[(\xi(i))^{3} \xi(j) \right] \\ + \sum_{i,j \text{ distinct}} 6f_{i}^{2} f_{j}^{2} \mathbb{E} \left[\xi(i)^{2} \xi(j)^{2} \right] + \sum_{i,j,k \text{ distinct}} 12f_{i}^{2} f_{j} f_{k} \mathbb{E} \left[\xi(i)^{2} \xi(j) \xi(k) \right] \\ + \sum_{i,j,k,l \text{ distinct}} 4! f_{i} f_{j} f_{k} f_{l} \mathbb{E} \left[\xi(i) \xi(j) \xi(k) \xi(l) \right]$$

 $\xi(j)$'s are 4-wise independent. So expectation of pair-wise, three-wise or four-wise products of $\xi(j)$'s are the product of the corresponding expectations.

Sketch: Variance

Using linearity of expectation

$$\mathbb{E} \left[X^{4} \right] = \sum_{i=1}^{n} f_{i}^{4} \mathbb{E} \left[\xi(i)^{4} \right] + \sum_{i \neq j} 4f_{i}^{3} f_{j} \mathbb{E} \left[(\xi(i))^{3} \xi(j) \right] \\ + \sum_{i,j \text{ distinct}} 6f_{i}^{2} f_{j}^{2} \mathbb{E} \left[\xi(i)^{2} \xi(j)^{2} \right] + \sum_{i,j,k \text{ distinct}} 12f_{i}^{2} f_{j} f_{k} \mathbb{E} \left[\xi(i)^{2} \xi(j) \xi(k) \right] \\ + \sum_{i,j,k,l \text{ distinct}} 4! f_{i} f_{j} f_{k} f_{l} \mathbb{E} \left[\xi(i) \xi(j) \xi(k) \xi(l) \right]$$

 $\xi(j)$'s are 4-wise independent. So expectation of pair-wise, three-wise or four-wise products of $\xi(j)$'s are the product of the corresponding expectations. So, for $\{i, j, k, l\}$ distinct

$$\begin{aligned} \xi(i)^2 &= \xi(i)^4 = 1 \\ \mathbb{E}\left[\xi(i)^3\xi(j)\right] &= \mathbb{E}\left[\xi(i)\xi(j)\right] = \mathbb{E}\left[\xi(i)\right] \mathbb{E}\left[\xi(j)\right] = 0 \cdot 0 = 0 \\ \mathbb{E}\left[\xi(i)^2\xi(j)\xi(k)\right] &= \mathbb{E}\left[\xi(j)\xi(k)\right] = 0 \\ \mathbb{E}\left[\xi(i)\xi(j)\xi(k)\xi(l)\right] &= \mathbb{E}\left[\xi(i)\right] \mathbb{E}\left[\xi(j)\right] \mathbb{E}\left[\xi(k)\right] \mathbb{E}\left[\xi(l)\right] = 0 \cdot 0 \cdot 0 \cdot 0 = 0 \end{aligned}$$

Sketches: Variance contd.

From Last Slide

$$\mathbb{E}\left[X^{4}\right] = \sum_{i=1}^{n} f_{i}^{4} \mathbb{E}\left[\xi(i)^{4}\right] + \sum_{i,j \text{ distinct}} 4f_{i}^{3}f_{j}\mathbb{E}\left[(\xi(i))^{3}\xi(j)\right]$$
$$+ \sum_{i \neq j} 6f_{i}^{2}f_{j}^{2}\mathbb{E}\left[\xi(i)^{2}\xi(j)^{2}\right] + \sum_{i,j,k \text{ distinct}} 12f_{i}^{2}f_{j}f_{k}\mathbb{E}\left[\xi(i)^{2}\xi(j)\xi(k)\right]$$
$$+ \sum_{i,j,k,l \text{ distinct}} 4!f_{i}f_{j}f_{k}f_{l}\mathbb{E}\left[\xi(i)\xi(j)\xi(k)\xi(l)\right]$$

$$\mathbb{E}\left[X^{4}\right] = \sum_{i=1}^{n} f_{i}^{4} + \sum_{i,j \text{ distinct}} 6f_{i}^{2}f_{j}^{2} \leq 3\left(\sum_{i=1}^{n} f_{i}^{2}\right)^{2}$$
$$\leq 3F_{2}^{2} \quad .$$

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AMS Sketch:
$$X = \sum_{i \in [n]} f_i \xi(i), \quad \xi : [n] \to \{1, -1\}$$
 4-wise indep. .

$$\mathbb{E} \left[X^2 \right] = F_2 \quad .$$

$$\operatorname{Var} \left[X^2 \right] = \mathbb{E} \left[X^4 \right] - (\mathbb{E} \left[X \right])^2 \le 3F_2^2 - F_2^2 = 2F_2^2$$

We can use Chebychev's inequality (Recall)

$$\Pr\left\{|Y - \mathbb{E}\left[Y\right]| > t\right\} < \frac{\operatorname{Var}\left[Y\right]}{t^2}$$

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for any real valued variable Y.

Designing estimator for F_2 contd.

- ► Need a random variable Y with expectation F₂ and variance at most e²F₂²/8.
- ► Why? Then, by Chebychev's inequality, we would have,

$$\Pr\left\{|Y - F_2| > \epsilon F_2\right\} \le \frac{\operatorname{Var}[Y]}{\epsilon^2 F_2^2} \le \frac{1}{8}$$

- ► Keep t independent sketches X₁, X₂,... X_t. Return averages of squares: Y = (X₁² + ... + X_t²) /t.
- ► Taking average preserves expectation, by linearity of expectation and X²_i are *i.d.* So E[Y] = E[X²₁] = F₂.
- Since, X_i²'s are independent, variance of their sum is the sum of their variances. So,

$$\operatorname{Var}[Y] = \frac{1}{t^2} t \operatorname{Var}[X_1^2] = 2F_2^2/t \; .$$

• Let
$$t = 16/\epsilon^2$$
. Then $\mathbb{E}[Y] = F_2$ and
 $\operatorname{Var}[Y] \le \epsilon^2 F_2^2/8$.

Therefore, by Chebychev's inequality

$$\mathsf{Pr}\left\{\left|Y-F_{2}\right| \leq \epsilon F_{2}\right\} \geq \frac{7}{8} \; .$$

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 We now use a standard argument for boosting confidence.

Boosting confidence from constant > 1/2 to $1 - \delta$

- Let A be a randomized algorithm.
- On input *I*, correct value is Y(I).
- Suppose A on input I returns (random) numeric value Ŷ(I). and the following guarantee:

$$\Pr\left\{|\hat{Y}(I) - Y(I)| < \epsilon Y(I)\right\} \ge \frac{7}{8}$$

To boost confidence to 1 − δ, run A independently on I s = O(log ¹/_δ) times to obtain

$$\hat{Y}_1(I),\ldots,\,\hat{Y}_s(I)$$
 .

Now return

$$\mathsf{med}\{\hat{Y}_1(I),\ldots,\hat{Y}_s(I)\}$$

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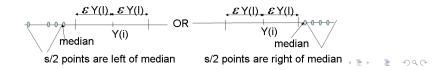
Boosting using Median: Analysis

► X_i = 0 if the *j*th run of A gives a "good answer" and is 1 otherwise.

$$X_j = \begin{cases} 0 & \text{if } |\hat{Y}_j(l) - Y(l)| < \epsilon Y(l) \\ 1 & \text{otherwise.} \end{cases}$$
$$\Pr{\{X_j = 1\} \le \frac{1}{8}}$$

- Let $X = X_1 + X_2 + \ldots + X_s$: count number of "bad" answers.
- $\mathbb{E}[X] \leq s/8.$
- The event $|\operatorname{med}(\hat{Y}_1(I),\ldots,\hat{Y}_k(I)) Y(I)| > \epsilon Y(I)$ implies

$$X \ge \frac{s}{2}$$



Boosting with median: Analysis

Chernoff's bound

Let X_1, \ldots, X_t be independent random variables taking values from $\{0, 1\}$ with $\mathbb{E}[X_i] = p_i$. Let $X = X_1 + X_2 + \ldots + X_t$ and $\mu = p_1 + \ldots + p_t$. Then, for $0 < \epsilon < 1$,

$$\Pr \{X > (1 + \epsilon)\mu\} < e^{-\mu\epsilon^2/3}$$

$$\Pr \{X < (1 - \epsilon)\mu\} < e^{-\mu\epsilon^2/2}$$

► By Chernoff's bound, with high probability, X should concentrate close to E [X] = s/8.

$$\Pr{\{X \ge s/2\}} \le \Pr{\{X \ge s/4\}} \le e^{-s/24}$$

This is at most δ if $s = O(\log \frac{1}{\delta})$.

AMS F_2 estimation algorithm

- Maintain *s* groups of *t* independent sketches X_j^r , $j = 1, 2, ..., t, r = 1, 2, ..., s, t = 16/\epsilon^2$ and $s = O(\log(1/\delta)).$
- In each group r, take average

$$Y_r = \operatorname{avg}_{j=1}^t (X_j^r)^2, \ r = 1, 2, \dots s$$
.

Return median of the averages

$$\hat{F}_2 = \operatorname{med}_{r=1}^s Y_j$$
 .

Property:

$$\Pr\left\{|\hat{F}_2 - F_2| < \epsilon F_2
ight\} \ge 1 - \delta$$
 .

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Space:

- Let |f_i| ≤ m. Each sketch ∑_i f_iξ(i) can be stored in log(mn) bits.
- Space = $O(\frac{1}{\epsilon^2} \log(1/\delta)) \times \log(mn)$.

Time to process stream update (i, v):

- Each sketch is updated.
- ► Requires evaluating degree 3 polynomial over 𝔽 : O(1) simple field operations.

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Randomness:

• Each sketch requires 4 log *n* random bits.

A Dimensionality Reduction View

- Suppose we keep $s = O(\log m)$ groups.
- ▶ Sketch as a map: $f \in \mathbb{R}^n$ to $sk(f) \in \mathbb{R}^{O(e^{-2}\log(m))}$.
- *m* streams with frequency vectors f^1, \ldots, f^m .
- Sketch is linear: therefore,

$$sk(f^i - f^j) = sk(f^i) - sk(f^j)$$

• So with probability $1 - \frac{1}{8m^2} \left(\frac{m^2}{2} + m\right) \ge 7/8$, we have

$$\begin{split} \|f^{i} - f^{j}\|_{2} &\in (1 \pm \epsilon) \mathsf{Medavg}(sk(f^{i}) - sk(f^{j})), \forall i, j. \\ \|f^{i}\| &\in (1 \pm \epsilon) \mathsf{Medavg}(sk(f^{i})), \forall i \end{split}$$

Medavg is not l₂ norm.

- ► A discrete metric space (X, d_X): X is a finite set of points, d_X(x, y) gives distance between points x and y in X. d_X function satisfies metric properties.
- (X, d_X) embeds into (Y, d_Y) with distortion D if there exists f : X → Y and a scaling constant c such that

 $c \cdot d_X(x,y) \leq d_Y(f(x),f(y)) \leq c \cdot D \cdot d_X(x,y), \quad \forall x,y \in X$.

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- ► [Bourgain] Every metric space can be embedded into ℓ₂ (any ℓ_p) with O(log n) distortion.
- [Johnson-Lindenstrauss(J-L)] There exists a randomized mapping f : ℝⁿ → ℝ^t, t = O(e⁻² log m) s.t. for any set S of m points from ℝⁿ

$$(1-\epsilon)||x-y||_2 \le ||f(x)-f(y)||_2 \le ||x-y||_2, \forall x, y \in S$$
.

 (1 + ε)-distortion for arbitrary ε: known to be impossible for ℓ_p to ℓ_q metric. Following is still possible:

there is a randomized function f : ℝⁿ → ℝ^t,
 t = O(1/ε² log m) s.t. for any set S from ℝⁿ having m points,

$$\|x - y\|_{p} \in (1 \pm \epsilon) d'(f(x), f(y)), \quad \forall x, y \in S$$

with probability 7/8.

But d' is not a metric.

- ► e-distortion implies: nearest neighbors are approximately preserved.
- ► k-d trees and other l₂-based geometric data structures can be used in much fewer dimensions.
- Time complexity of most geometric algorithms, including NN, is exponential in dimension.

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► A basic step in reducing this "curse of dimensionality".

Normal Distribution

• Gaussian distribution (Normal distribution): $X \sim N(\mu, \sigma^2).$

•
$$\mathbb{E}[X] = \mu$$
, $\operatorname{Var}[X] = \sigma^2$.

Probability density function:

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- ► Standard Normal distribution: *N*(0, 1).
- Stability: Sum of independent normally distributed variates is normally distributed.
 X_i ~ N(μ_i, σ_i²), i = 1, 2, ..., k, X_i's independent. Then,

$$X_1 + \ldots + X_k \sim N(\mu_1 + \ldots + \mu_k, \sigma_1^2 + \ldots + \sigma_k^2)$$

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Gamma distribution

- Gamma(k, θ), k = Gamma parameter, θ = scale factor (non-negative).
- Pdf: $f(x; k, \theta) = \frac{1}{\theta^k \Gamma(k)} x^{k-1} e^{-x/\theta}$.
- $\blacktriangleright \mathbb{E}[X] = k\theta.$
- If $X \sim N(0, \sigma^2)$, then, $X^2 \sim \text{Gamma}(1/2, 2\sigma^2)$.
- ► Scaling Property: If $X \sim \text{Gamma}(k, \theta)$, then, $aX \sim \text{Gamma}(k, a\theta)$.
- Sum of Gamma variates is Gamma distributed if scale factors are same.

Let $X_i \sim \text{Gamma}(k_i, \theta)$ and independent. Then,

$$X_1 + \ldots + X_r \sim \text{Gamma}(k_1 + k_2 + \ldots + k_r, \theta)$$

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- Let $\xi(j) \sim N(0, 1)$ for $j \in [n]$.
- ξ(j)'s are (fully) independent. Ignore randomness/space/time required for now.
- Consider sketch

$$X = \sum_{i=1}^n f_i \xi(i) \; .$$

By stability property of normal distr.

$$X \sim N(0,F_2)$$
 .

Problem reduces to: Estimate variance of X.

Gaussian sketches

- ► Let $X_1, X_2, ..., X_t$ be independent Gaussian sketches.
- Define
 Y = X₁² + ... + X_t².
 Each X_j² ~ Gamma (1/2, 2F₂). Therefore,
 Y ~ Gamma(t/2, 2F₂).
- $\mathbb{E}[Y] = tF_2$.
- Need Tail probabilities:

 $\Pr\{Y > (1 + \epsilon)F_2\}$ and $\Pr\{Y < (1 - \epsilon)F_2\}$.

Tail Bounds for Gamma Distribution

Property. Let $Y \sim Gamma(t, \theta)$. Then, for $\epsilon < 1$,

$$\Pr\left\{Y \in (1 \pm \epsilon)\mathbb{E}\left[Y\right]\right\} \leq \frac{2e^{-\epsilon^2 t/6}}{\epsilon\sqrt{2\pi(t-1)}}.$$

• Let
$$Y = (X_1^2 + \ldots + X_{2t}^2)/t \sim \text{Gamma}(t, F_2/t)$$

• Let
$$t = O(e^{-2} \log(m))$$
.

By concentration property,

$$Y \in (1 \pm \epsilon)F_2$$
 with prob. $1 - \frac{1}{8m^2}$

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Another view of mapping: J-L Lemma

• $t \times n$ matrix A, entries $z_{i,j}$ drawn from N(0, 1) i.i.d.

$$A = \begin{bmatrix} z_{1,1} & z_{1,2} & \dots & z_{1,n} \\ z_{2,1} & z_{2,1} & \dots & z_{2,n} \\ \vdots & \vdots & \vdots \\ z_{t,1} & z_{t,2} & \dots & z_{t,n} \end{bmatrix}$$

- ► $x \in \mathbb{R}^n$, $x \mapsto Ax$, $||Ax||_2 \in (1 \pm \epsilon) ||x||_2$ with prob. $1 - 1/m^{O(1)}$.
- By linearity, A(x y) = Ax Ay.
- Let $t = O(e^{-2} \log m)$. For any set S of m points,

$$\|Ax - Ay\|_2 \in (1 \pm \epsilon) \|x - y\|_2, \quad \forall x, y \in S$$

with probability $1 - 1/m^2$.

- Estimating ℓ_p norms for 0 .
- Heavy Hitters: HH[¢]_p
 - If $|f|_i > \phi ||f||_p$, then, $i \in HH_p^{\phi}$.
 - ▶ Parameter ϕ' : If $|f|_i < \phi' ||f||_p$, then, $i \notin HH_p^{\phi,\phi'}$.

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• Estimating ℓ_p norms for p > 2.

Conclusion (Sketching Streams)

THANK YOU!

