

Introduction to Computational Geometry

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Outline

- 1 Introduction
- 2 Area Computation of a Simple Polygon
- 3 Point Inclusion in a Simple Polygon
- 4 Convex Hull: An application of incremental algorithm
- 5 Art Gallery Problem: A study of combinatorial geometry

Introduction

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- People deal more with **straight or flat objects** (lines, line segments, polygons) or **simple curved objects** as circles, than with high degree algebraic curves.
- This branch of study is around thirty years old if one assumes Michael Ian Shamos's thesis [6] as the starting point.

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- Programming in CG is a little difficult. Fortunately, libraries like **LEDA** [7] and **CGAL** [8] are now available. These libraries implement various data structures and algorithms specific to CG.
- CG algorithms suffer from the curse of degeneracies. So, we would make certain simplifying assumptions at times like **no three points are collinear**, **no four points are cocircular**, etc.

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- First we consider some geometric primitives, that is, problems that arise frequently in computational geometry.

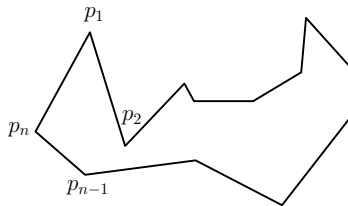
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Area Computation

Problem

Given a simple polygon P of n vertices, compute its area.



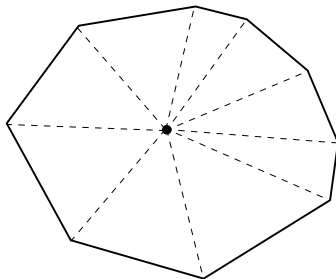
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Area of a convex polygon

Find a point inside P , draw n triangles and compute the area.



Area Computation

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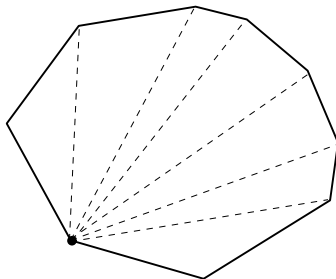
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A better idea for convex polygon

We can **triangulate** P by **non-crossing diagonals** into $n - 2$ triangles and then find the area.



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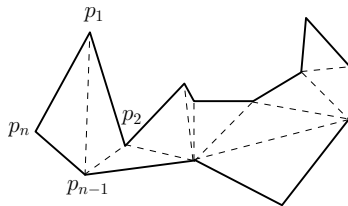
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We can **triangulate** P by **non-crossing diagonals** into $n - 2$ triangles and then find the area.

A better idea for simple polygon

We can do likewise.



Area Computation

Result

If P be a simple polygon with n vertices with coordinates of the vertex p_i being (x_i, y_i) , $1 \leq i \leq n$, then twice the area of P is given by

$$2\mathcal{A}(P) = \sum_{i=1}^n (x_i y_{i+1} - y_i x_{i+1})$$

Polygon Triangulation

Theorem

Any simple polygon can be triangulated.

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The proof is by induction on n . □

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Time complexity

We can **triangulate** P by a very complicated $O(n)$ algorithm [2]
OR by a *more or less simple* $O(n \log n)$ time algorithm [1].

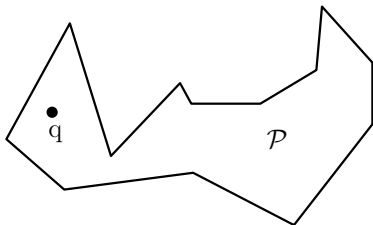
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Point Inclusion

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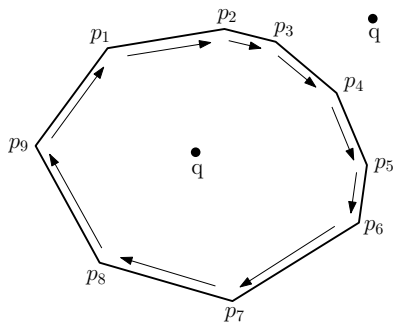
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What if P is convex?

Easy in $O(n)$. Takes a little effort to do it in $O(\log n)$. Left as an **exercise**.



q is always to the right if $q \in P$,
else, it varies

Point Inclusion

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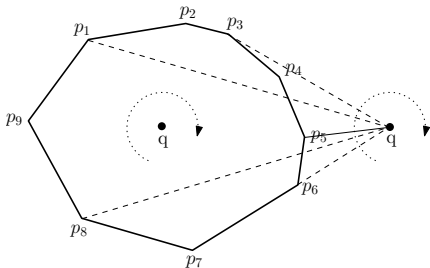
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Another idea for convex polygon

Stand at q and walk around the polygon. We can show the same result for a simple polygon also.

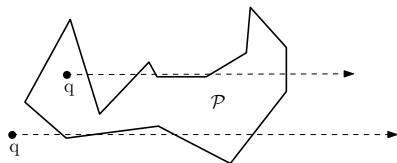


Total angular turn around q is 2π if $q \in P$,
else, 0

Point Inclusion

Another technique: Ray Shooting

Shoot a **ray** and count the number of **crossings** with edges of P . If it is odd, then $q \in P$. If it is even, then $q \notin P$. Some degenerate cases need to be handled. Time taken is $O(n)$.



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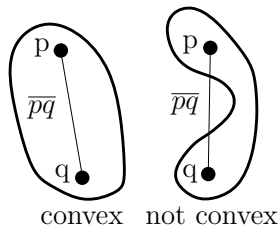
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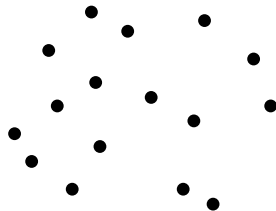
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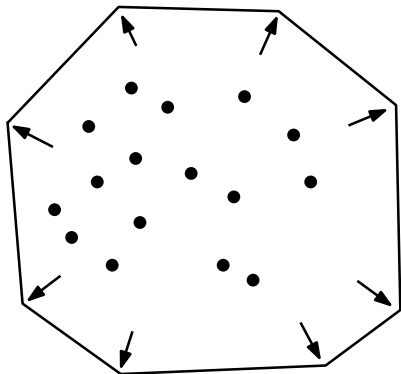
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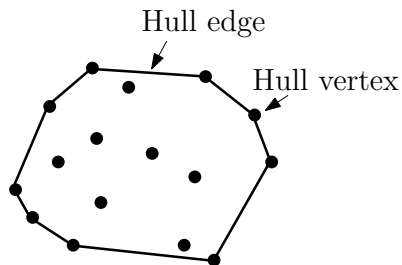
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Convex Hull Problem

Problem

Given a set of points \mathcal{P} in the plane, compute the convex hull $CH(\mathcal{P})$ of the set \mathcal{P} .

A Naive Algorithm

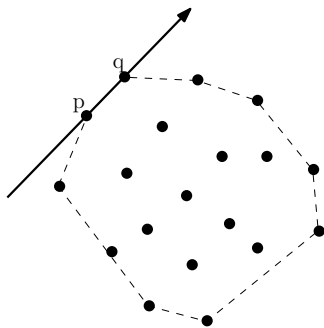
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- Consider all line segments determined by $\binom{n}{2} = O(n^2)$ pairs of points.

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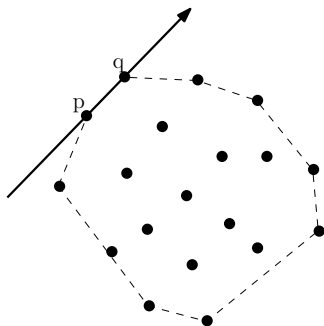
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- If a line segment has all the other $n - 2$ points on one side of it, then it is a hull edge.



A Naive Algorithm

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- If a line segment has all the other $n - 2$ points on one side of it, then it is a hull edge.
- We need $\binom{n}{2}(n - 2) = O(n^3)$ time.



Towards a Better Algorithm

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- Better characterizations lead to better algorithms.

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- Better characterizations lead to better algorithms.
- How much better can we make?
- Leads to the notion of **lower bound of a problem**.
- The problem of Convex Hull has a lower bound of $\Omega(n \log n)$.
This can be shown by a reduction from the problem of sorting which also has a lower bound of $\Omega(n \log n)$.

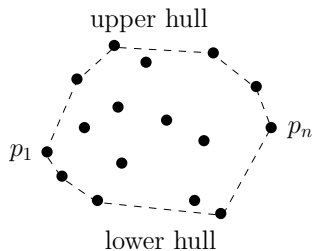
Well Known Algorithms

- **Grahams scan**, time complexity $O(n \log n)$.
(Graham, R.L., 1972)
- **Divide and conquer algorithm**, time complexity $O(n \log n)$.
(Preparata, F. P. and Hong, S. J., 1977)
- **Jarvis's march** or **gift wrapping algorithm**, time complexity $O(nh)$ where h is the number of vertices of the convex hull.
(Jarvis, R. A., 1973)
- Most efficient algorithm to date is based on the idea of Jarvis's march, time complexity $O(n \log h)$.
(T. M. Chan, 1996)

Definitions

A better characterization

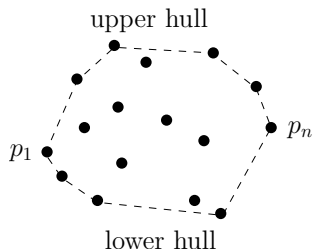
- Consider a walk in clockwise direction on the vertices of a closed polygon.



Definitions

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- Consider a walk in clockwise direction on the vertices of a closed polygon.
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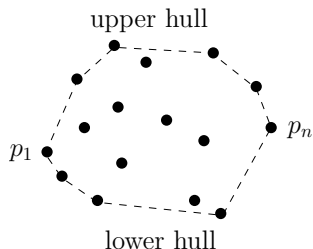


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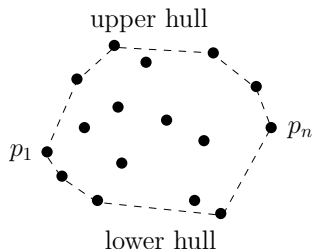
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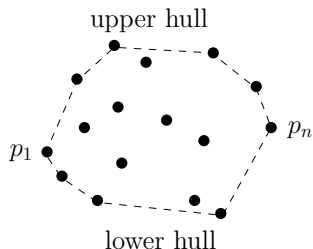
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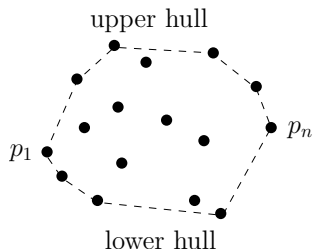
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- Sort the points in \mathcal{P} from left to right.



The Algorithm

Input: A set P of n points in the plane

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Output: Convex Hull of P

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for $i = 3$ to n {

Append $p[i]$ to L_U ;

while(L_U contains more than two points AND

the last three points in L_U

do not make a right turn) {

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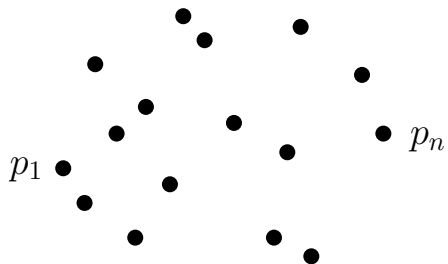
Delete the middle of the last

three points from L_U ;

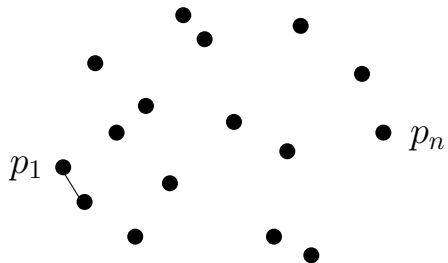
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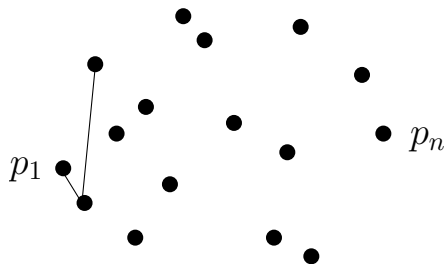
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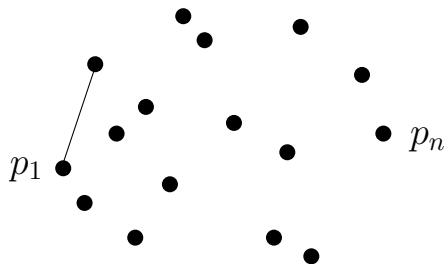
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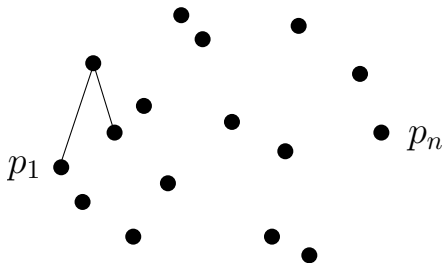
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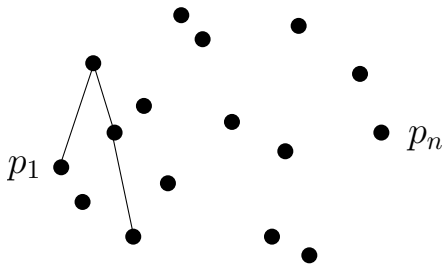
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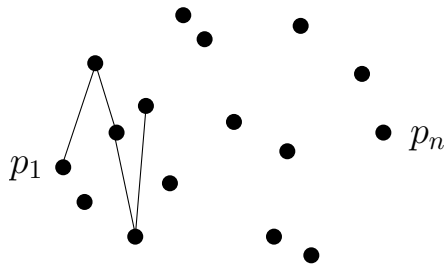
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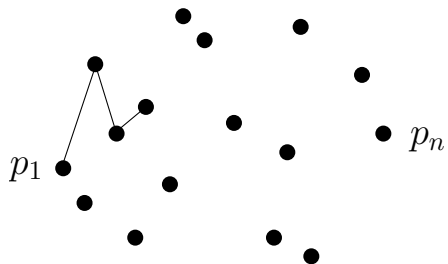
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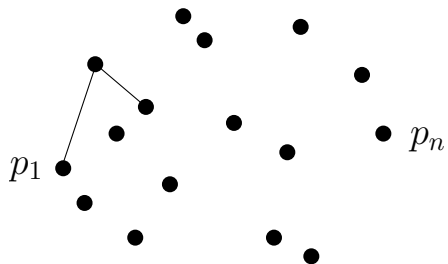
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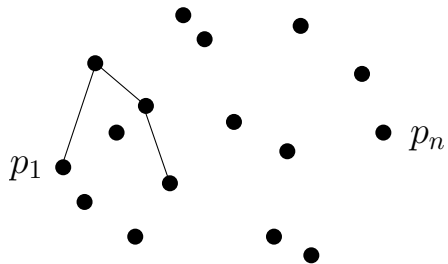
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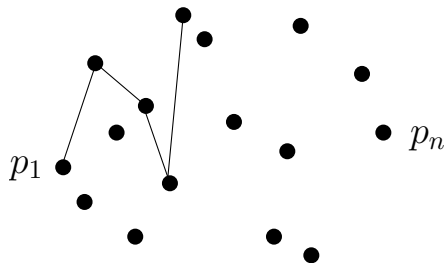
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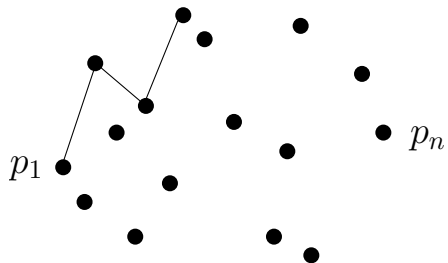
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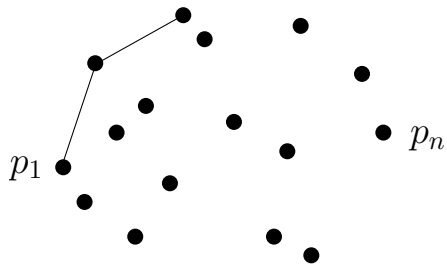
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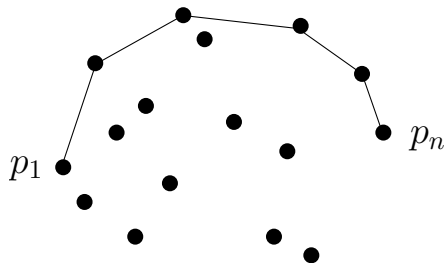
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- Hence, the total time complexity is $O(n \log n)$.

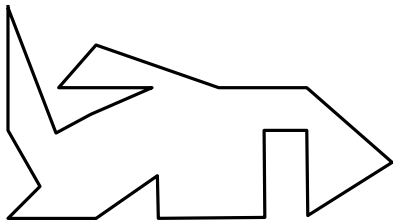
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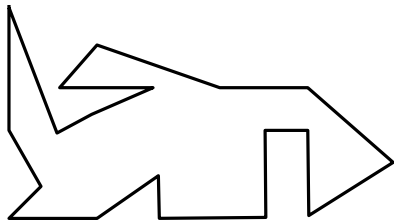
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Hardness

The above problem is NP-Hard.



Art Gallery Problem

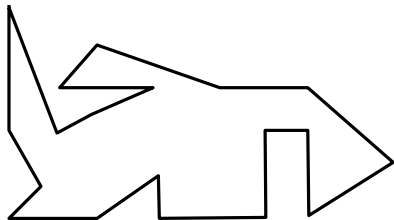
The problem

Given a simple polygon \mathcal{P} of n vertices, find the minimum number of cameras that can guard \mathcal{P} .

Hardness

The above problem is NP-Hard.

Simpler Version



Art Gallery Problem

The problem

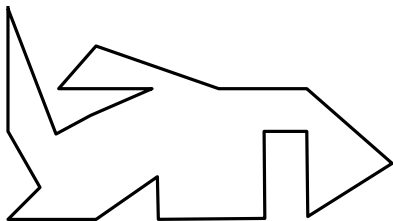
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Simpler Version

- Can we find, as a function of n , the number of cameras that suffices to guard \mathcal{P} ?



Art Gallery Problem

The problem

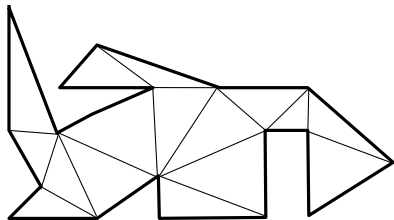
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Simpler Version

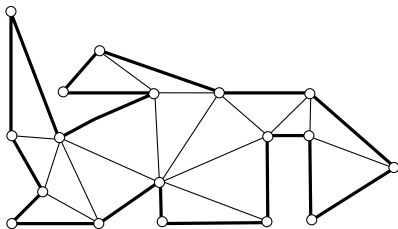
- Can we find, as a function of n , the number of cameras that suffices to guard \mathcal{P} ?
- Recall \mathcal{P} can be triangulated into $n - 2$ triangles. Place a guard in each triangle.



Art Gallery Problem

Can the bound be reduced?

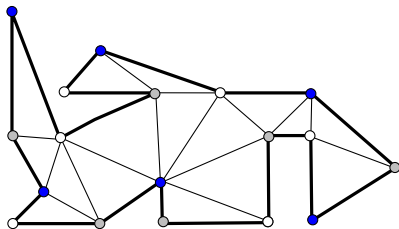
- Place guards at the vertices of the triangles.



Art Gallery Problem

Can the bound be reduced?

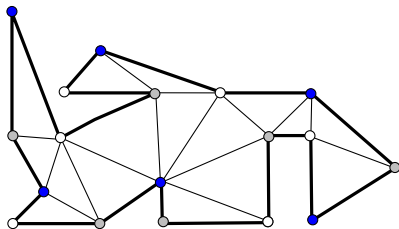
- Place guards at the vertices of the triangles.
- We do a 3-coloring of the vertices of \mathcal{T} . Each triangle of \mathcal{T} has a blue, gray and white vertex.



Art Gallery Problem

Can the bound be reduced?

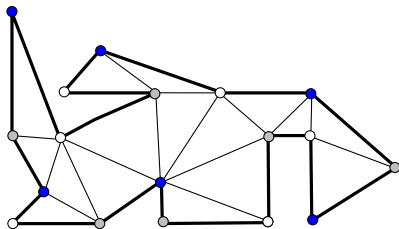
- Place guards at the vertices of the triangles.
- We do a 3-coloring of the vertices of \mathcal{T} . Each triangle of \mathcal{T} has a blue, gray and white vertex.
- Choose the smallest color class to guard \mathcal{P} .



Art Gallery Problem

Can the bound be reduced?

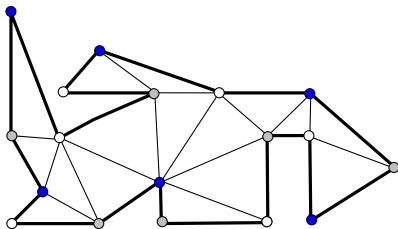
- Place guards at the vertices of the triangles.
- We do a 3-coloring of the vertices of \mathcal{T} . Each triangle of \mathcal{T} has a blue, gray and white vertex.
- Choose the smallest color class to guard \mathcal{P} .
- Hence, $\lfloor \frac{n}{3} \rfloor$ guards suffice.



Art Gallery Problem

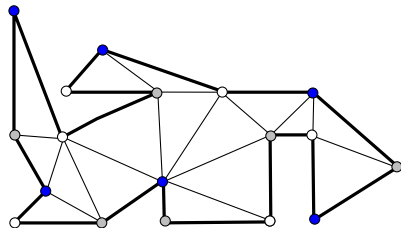
Can the bound be reduced?

- Place guards at the vertices of the triangles.
- We do a 3-coloring of the vertices of \mathcal{T} . Each triangle of \mathcal{T} has a blue, gray and white vertex.
- Choose the smallest color class to guard \mathcal{P} .
- Hence, $\lfloor \frac{n}{3} \rfloor$ guards suffice.
- But, does a 3-coloring always exist?



Art Gallery Problem

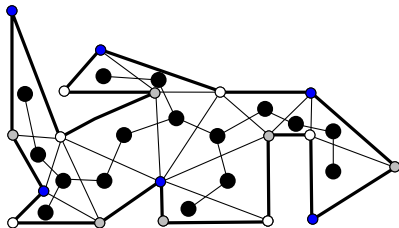
A 3-coloring always exist



Art Gallery Problem

A 3-coloring always exist

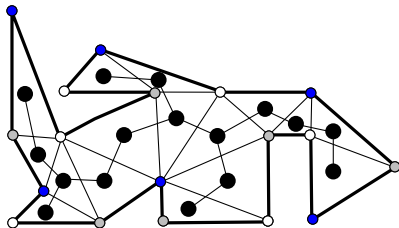
- Consider the dual graph \mathcal{G}_T of T of \mathcal{P} .



Art Gallery Problem

A 3-coloring always exist

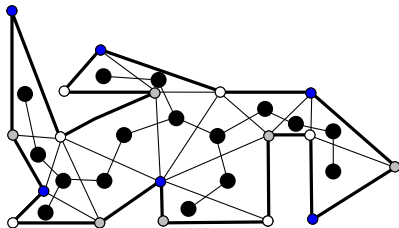
- Consider the dual graph $\mathcal{G}_{\mathcal{T}}$ of \mathcal{T} of \mathcal{P} .
- $\mathcal{G}_{\mathcal{T}}$ is a tree as \mathcal{P} has no holes.



Art Gallery Problem

A 3-coloring always exist

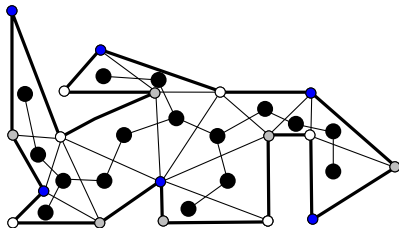
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- Do a DFS on $\mathcal{G}_{\mathcal{T}}$ to obtain the coloring.



Art Gallery Problem

A 3-coloring always exist

- Consider the dual graph $\mathcal{G}_{\mathcal{T}}$ of \mathcal{T} of \mathcal{P} .
- $\mathcal{G}_{\mathcal{T}}$ is a tree as \mathcal{P} has no holes.
- Do a DFS on $\mathcal{G}_{\mathcal{T}}$ to obtain the coloring.
- Place guards at those vertices that have color of the minimum color class. Hence, $\lfloor \frac{n}{3} \rfloor$ guards are sufficient to guard \mathcal{P} .



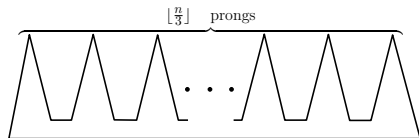
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Necessity?

Are $\lfloor \frac{n}{3} \rfloor$ guards sometimes necessary?









Art Gallery Theorem

Final Result

For a simple polygon with n vertices, $\lfloor \frac{n}{3} \rfloor$ cameras are always sufficient and occasionally necessary to have every point in the polygon visible from at least one of the cameras.

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<http://www.cgal.org>



[http:
//en.wikipedia.org/wiki/Computational_geometry](http://en.wikipedia.org/wiki/Computational_geometry)

Thank you!